

An aerial photograph of the ASTRON radio telescope facility. The facility is located in a green, marshy area with several large, dark, rectangular solar panel arrays arranged in a grid pattern. A winding river or canal flows around the facility. The text "Introduction to Low-Frequency Radio Astronomy" is overlaid in large, white, bold letters.

Introduction to Low-Frequency Radio Astronomy

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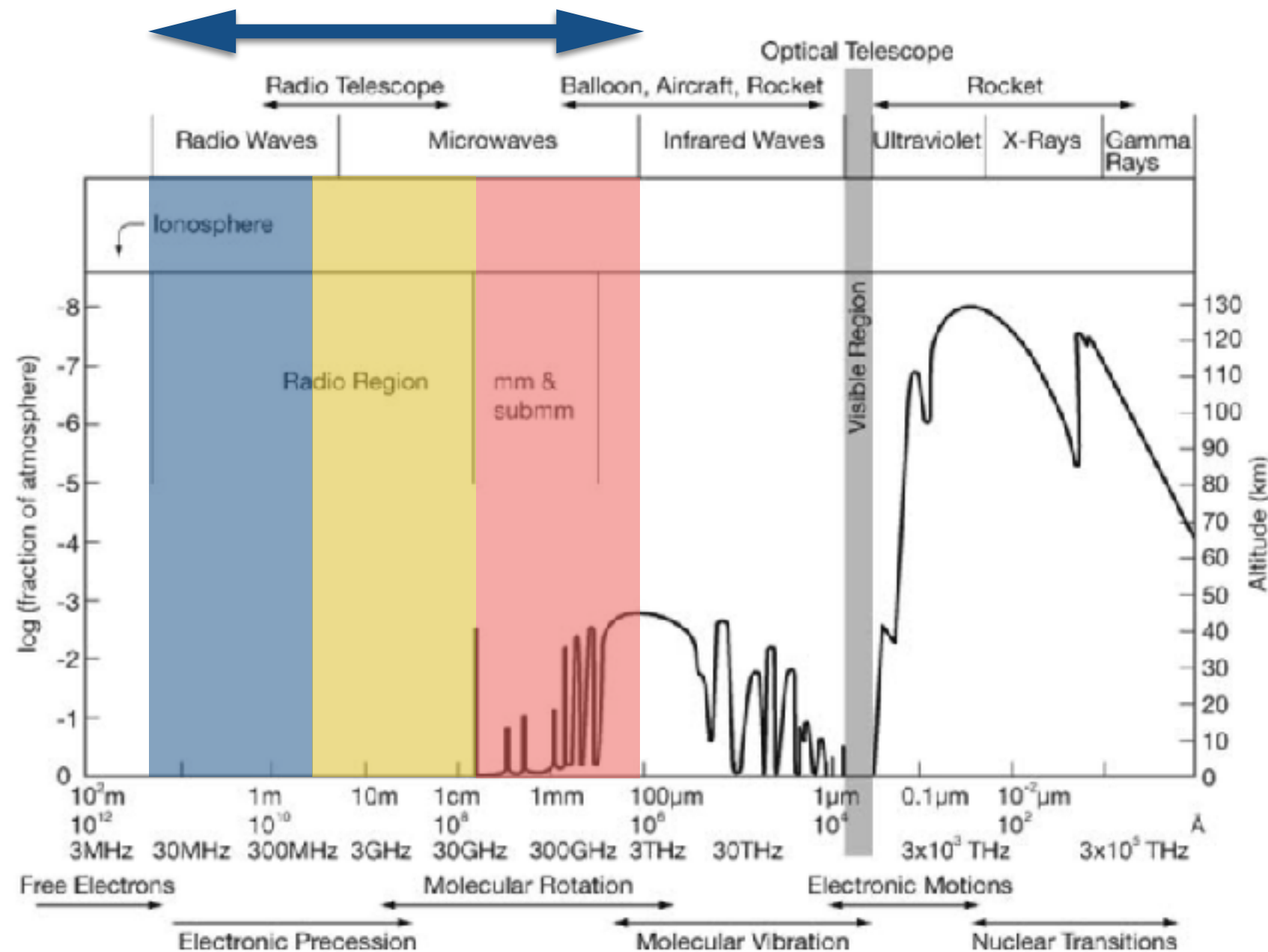
Preamble

- **AIM:** This lecture aims to give a general introduction to low frequency radio astronomy, focusing on the issues that you must consider and the differences with observations with other telescopes.
- **OUTLINE:**
 1. The radio sky and historical developments
 2. The response of a dipole antenna
 3. The response of an interferometer
 4. Low frequency radio telescopes



1.1 The Radio Window

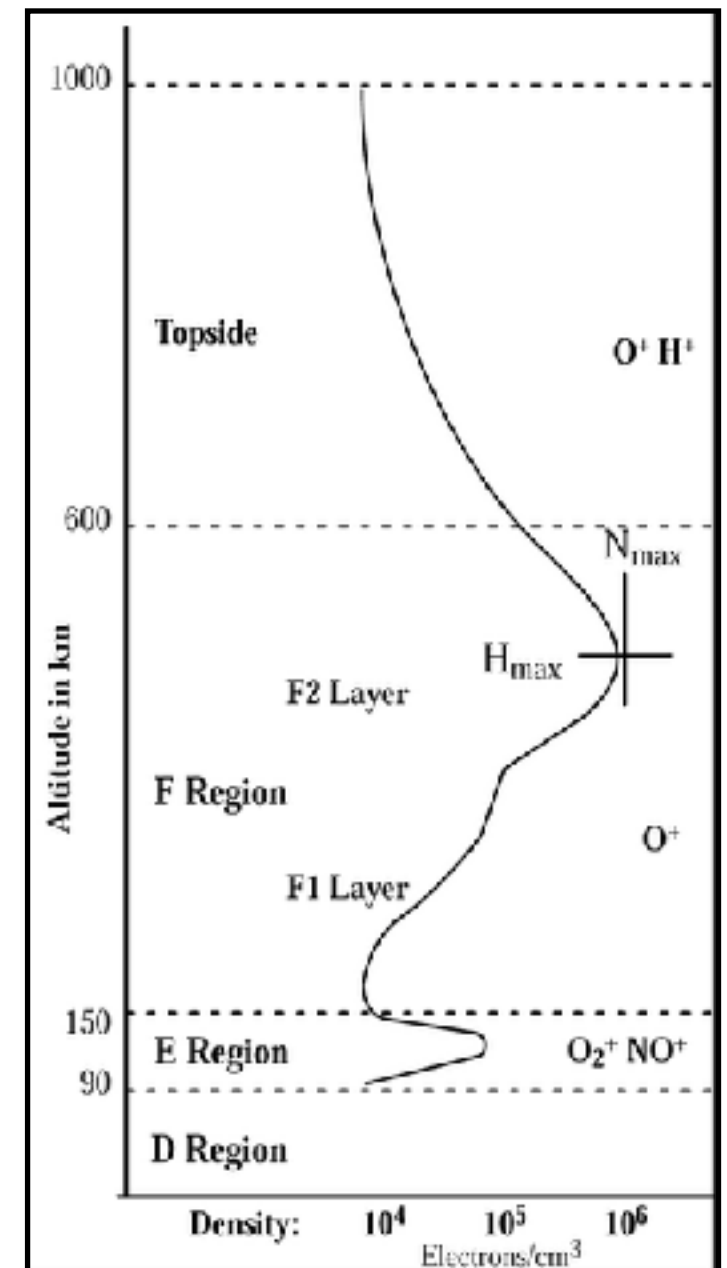
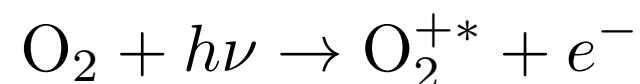
- Radio Astronomy is the study of radiation from celestial sources at frequencies between $\nu \sim 10$ MHz to 1 THz (10^7 Hz to 10^{12} Hz).



- The observing window is constrained by atmospheric absorption / emission and refraction.
 - 1) Charged particles in the ionosphere reflect radio waves back into space at < 10 MHz.
 - 2) Vibrational transitions of molecules have similar energy to infra-red photons and absorb the radiation at > 1 GHz (completely by ~ 300 GHz).

1.2 The low-frequency cut-off

- The ionosphere consists of a plasma of charged particles (conducting layers).
- The observing conditions are dependent on the electron density, i.e. the solar conditions (space weather), since the ionisation is due to the ultra-violet radiation field from the Sun,



2.4 Propagation of radio waves through a (cold) conducting medium

- A plasma consists of an ionised gas of ions and free electrons that has no net charge. A cold plasma is one where the thermal motions of the electrons is negligible.
- Important for understanding
 1. the reflection and transmission through our atmosphere; and
 2. the dispersion of radio waves at low frequencies.
- As we are dealing with the propagation of radio waves through a conducting medium, we must start with Maxwell's equations.

$$\nabla \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$$

Electric field intensity \swarrow

$$\nabla \times \vec{B} = \mu_0 \vec{J} + \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t}$$

Magnetic induction \swarrow Current density \swarrow

where,

$$c = \frac{1}{\sqrt{\mu_0 \epsilon_0}}$$

permeability permittivity

$$\vec{J} = \sigma \vec{E}$$

Conductivity \swarrow

- First, consider the curl of the B-field in terms of the E-field, and take the conductivity into account,

$$\nabla \times \vec{B} = \mu_0 \sigma \vec{E} + \mu_0 \epsilon_0 \dot{\vec{E}}$$

- Next we have to take the curl of the E-field and differentiate with respect to time,

$$\nabla \times (\nabla \times \vec{E}) = \frac{d}{dt}(\nabla \times \vec{B}) = \mu_0 \sigma \dot{\vec{E}} + \mu_0 \epsilon_0 \ddot{\vec{E}}$$

$$\nabla^2 \vec{E} = \mu_0 \sigma \dot{\vec{E}} + \mu_0 \epsilon_0 \ddot{\vec{E}}$$

$$\nabla^2 \vec{E} - \mu_0 \sigma \dot{\vec{E}} - \mu_0 \epsilon_0 \ddot{\vec{E}} = 0$$

- This gives the wave equation for the electric field in a conducting material, which we can evaluate by considering a solution given by a harmonic wave of the form,

$$E(r, t) = E_0 e^{-i(\omega t - kr)}$$

$$\nabla^2 E(r, t) = -k^2 E(r, t)$$

$$\dot{E}(r, t) = E_0 e^{-i(\omega t - kr)} \cdot -i\omega = -i\omega E(r, t)$$

$$\ddot{E}(r, t) = -i\omega E_0 e^{-i(\omega t - kr)} \cdot -i\omega = -\omega^2 E(r, t)$$

giving

$$-k^2 E(r, t) - \mu_0 \sigma \cdot -i\omega E(r, t) - \mu_0 \epsilon_0 \cdot -\omega^2 E(r, t) = 0$$

$$-k^2 + i\mu_0 \sigma \omega + \mu_0 \epsilon_0 \omega^2 = 0$$

$$k^2 = \frac{\omega^2}{c^2} + i \frac{\sigma \omega}{c^2 \epsilon_0}$$

$$c = \frac{1}{\sqrt{\mu_0 \epsilon_0}}$$

- Free electrons in the plasma are accelerated by the E-field, with an equation of motion,

$$m_e \dot{v} = -e \vec{E}(r, t)$$

with solution,

$$v = -i \frac{e}{m_e \omega} \vec{E}(r, t)$$

- These motions of the charge will result in a current with a density of,

$$\vec{J}(r, t) = -n_e e v = i \frac{n_e e^2}{m_e \omega} \vec{E}(r, t) = \sigma \vec{E}(r, t)$$

where the conductivity is purely imaginary

$$\sigma = i \frac{n_e e^2}{m_e \omega}$$

- Recall our equation of the wave vector

$$k^2 = \frac{\omega^2}{c^2} + i \frac{\sigma \omega}{c^2 \epsilon_0}$$

$$\begin{aligned}
 k^2 &= \frac{\omega^2}{c^2} + i \frac{\omega}{c^2 \epsilon_0} \cdot i \frac{n_e e^2}{m_e \omega} \\
 &= \frac{\omega^2}{c^2} - \frac{n_e e^2}{c^2 \epsilon_0 m_e} \\
 &= \frac{\omega^2}{c^2} \left(1 - \frac{n_e e^2}{\omega^2 \epsilon_0 m_e} \right)
 \end{aligned}$$

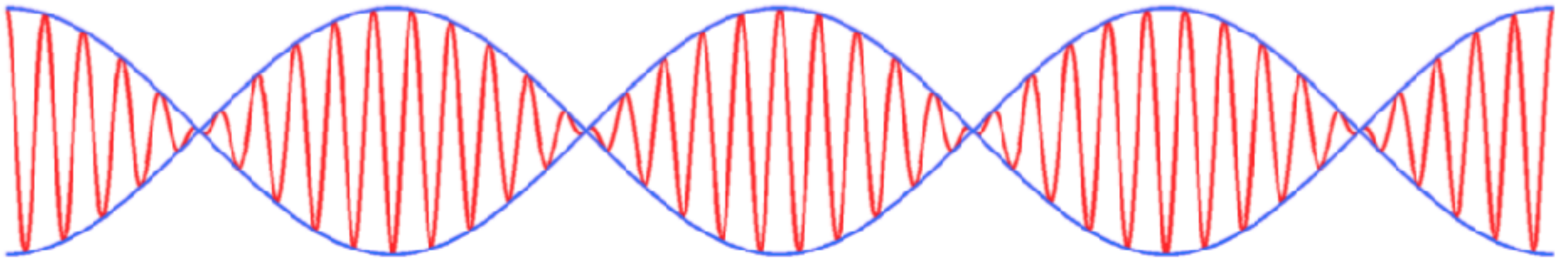
$$k^2 = \frac{\omega^2}{c^2} \left(1 - \frac{\omega_p^2}{\omega^2} \right) \quad \text{where} \quad \omega_p = \sqrt{\frac{n_e e^2}{\epsilon_0 m_e}}$$

- The plasma frequency defines the natural resonant frequency of a plasma oscillation and is dependent purely on the **number density of the free electrons** (in free-space).
- **Phase velocity:** the rate that any one frequency component travels through a medium.

$$v_p \equiv \frac{\omega}{k}$$

- **Group velocity:** the rate that the wave envelop travels through a medium.

$$v_g \equiv \frac{d\omega}{dk}$$



- Substituting our equation for the wave vector into the equation for the phase velocity gives,

$$v_p^2 \equiv \frac{\omega^2}{k^2} = \frac{\omega^2}{\frac{\omega^2}{c^2} \left(1 - \frac{\omega_p^2}{\omega^2}\right)}$$

$$v_p = \frac{c}{\sqrt{\left(1 - \frac{\omega_p^2}{\omega^2}\right)}}$$

- Similarly, we can calculate the group velocity as,

$$v_g \equiv \frac{d\omega}{dk} = \frac{1}{dk/d\omega} \qquad v_g = c \sqrt{1 - \frac{\omega_p^2}{\omega^2}}$$

- Both the group and phase velocities are dependent on frequency, but when $\omega < \omega_p$, then the group velocity is 0 and waves cannot propagate through the plasma.
- From the definition of the refractive index and taking the phase velocity,

$$n = \sqrt{1 - \frac{\omega_p^2}{\omega^2}} \qquad n = \frac{c}{v}$$

Worked example: What is the cut-off frequency for LOFAR observations carried out when the electron density is $N_e = 2.5 \times 10^5 \text{ cm}^{-3}$ (night time) and $N_e = 1.5 \times 10^6 \text{ cm}^{-3}$ (day time)?

$$\nu_p[\text{Hz}] = 8.97 \times 10^3 \sqrt{\frac{2.5 \times 10^5}{[\text{cm}^{-3}]}} = 4.5 \text{ MHz} \quad (\text{night time})$$

$$\nu_p[\text{Hz}] = 8.97 \times 10^3 \sqrt{\frac{1.5 \times 10^6}{[\text{cm}^{-3}]}} = 11 \text{ MHz} \quad (\text{day time})$$

- At frequencies,
 1. $\omega < \omega_p$: n^2 is **negative**, reflection ($\nu < 10 \text{ MHz}$),
 2. $\omega > \omega_p$: n^2 is **positive**, refraction ($10 \text{ MHz} < \nu < 10 \text{ GHz}$),
 3. $\omega \gg \omega_p$: n^2 is **unity** ($\nu > 10 \text{ GHz}$).

- To investigate the effect of the dispersive effect on the group velocity, let's consider a set of pulses that move with the group velocity, from a series expansion we find,

$$\frac{1}{v_g} = \frac{1}{c} \left(1 + \frac{1}{2} \frac{\nu_p^2}{\nu^2} \right)$$

the arrival time of these pulses will be delayed by,

$$\tau_D = \int_0^L \frac{dl}{v_g} = \frac{1}{c} \int_0^L \left(1 + \frac{1}{2} \frac{\nu_p^2}{\nu^2} \right) dl = \frac{1}{c} \int_0^L \left(1 + \frac{1}{2} \frac{n_e e^2}{4\pi^2 m_e \epsilon_0 \nu^2} \right) dl$$

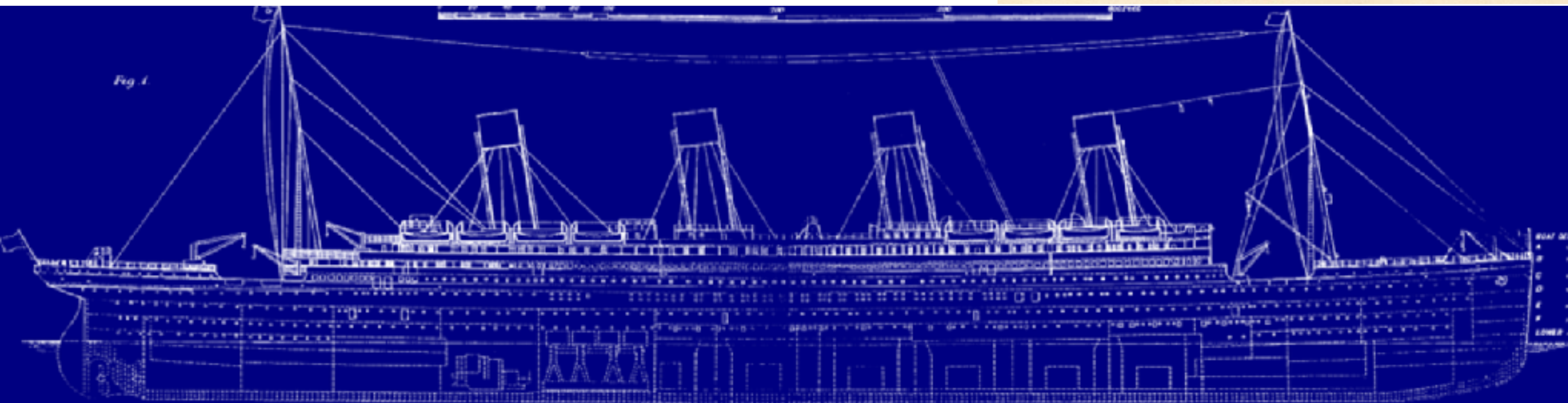
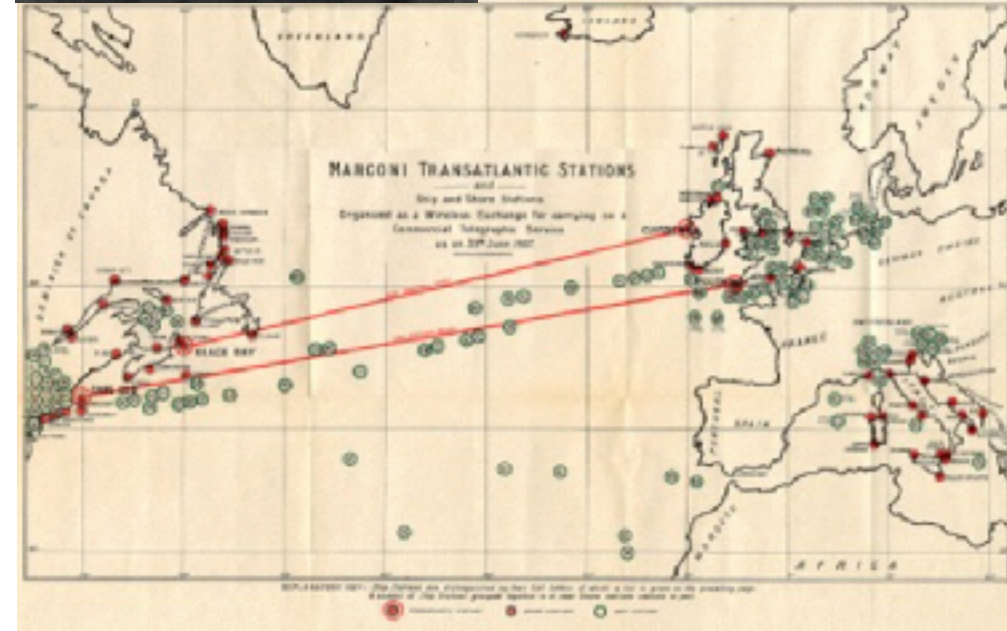
$$\tau_D = \frac{L}{c} + \frac{e^2}{8\pi^2 c m_e \epsilon_0 \nu^2} \int_0^L n_e dl$$

- This is a dispersive effect (the arrival time changes as a function of frequency).

- Long distance communication developed by Marconi & Ferdinand Braun - Nobel Prize 1909

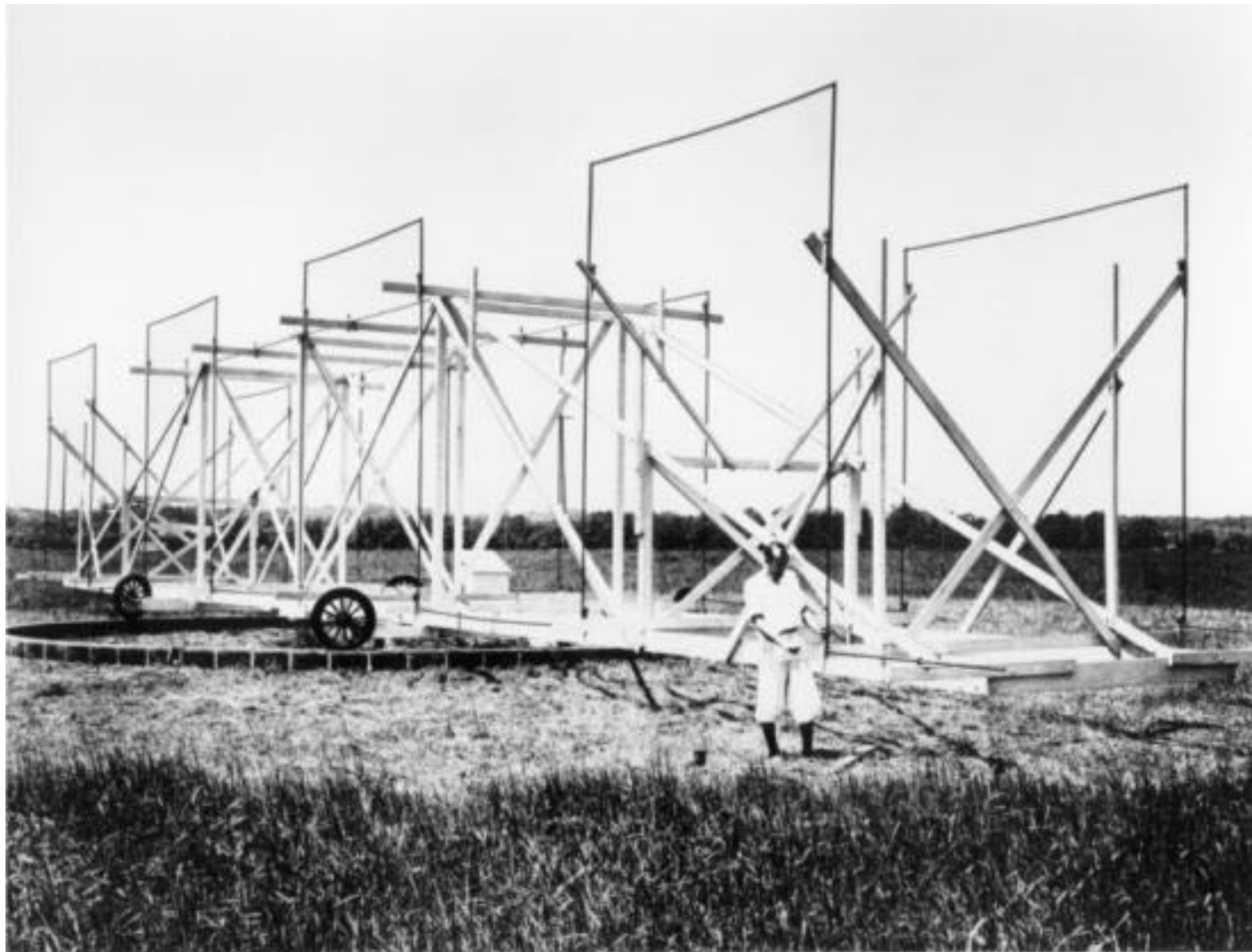
Evolution of frequency over the years

- pre-1920: <100 kHz.
- ca. 1920: shift to 1.5 MHz.
- post-1920: 10s of MHz (more voice channels, less effected by the ionosphere and thunderstorms).
- Research labs sprung up in early-1900s



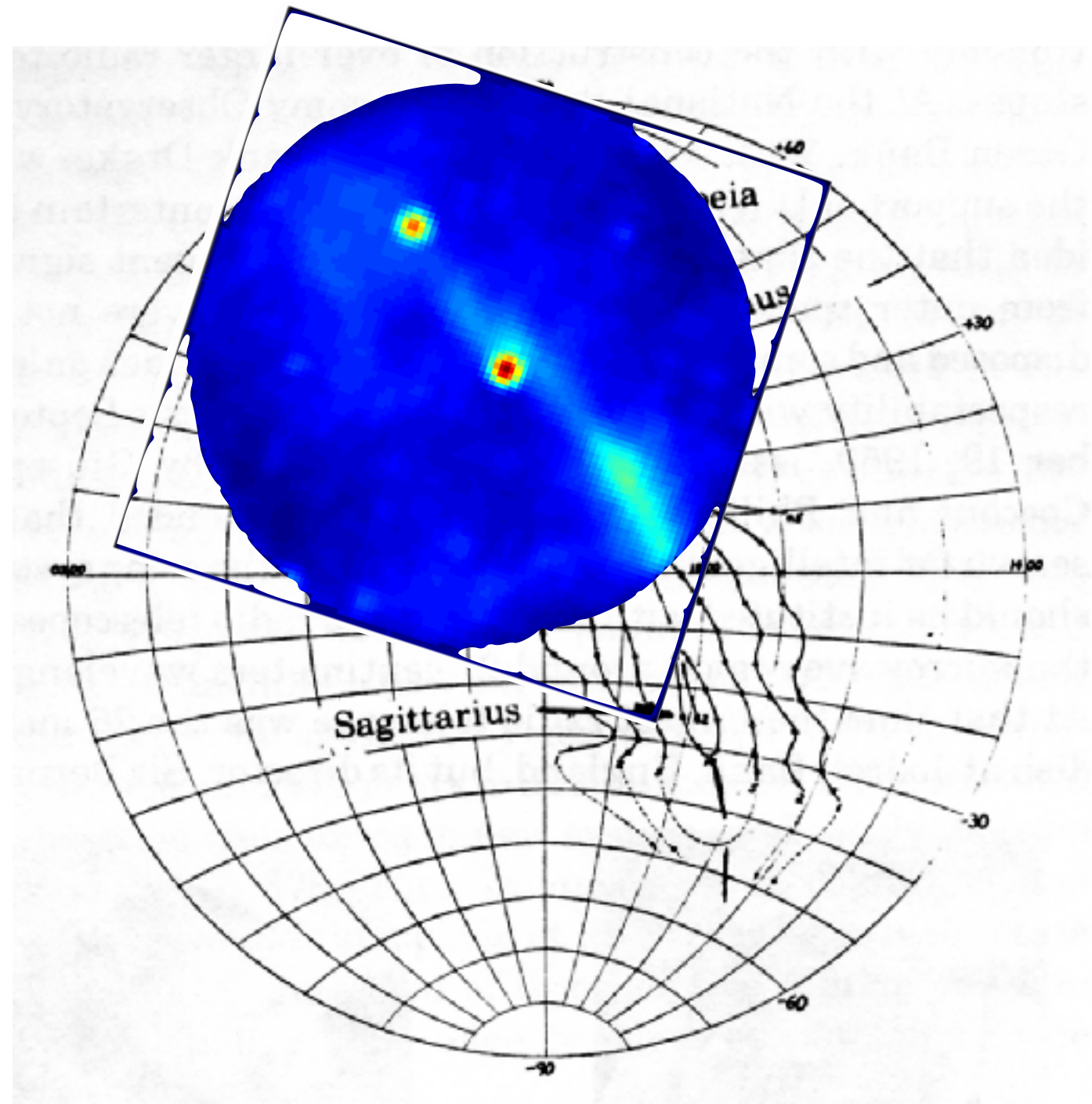
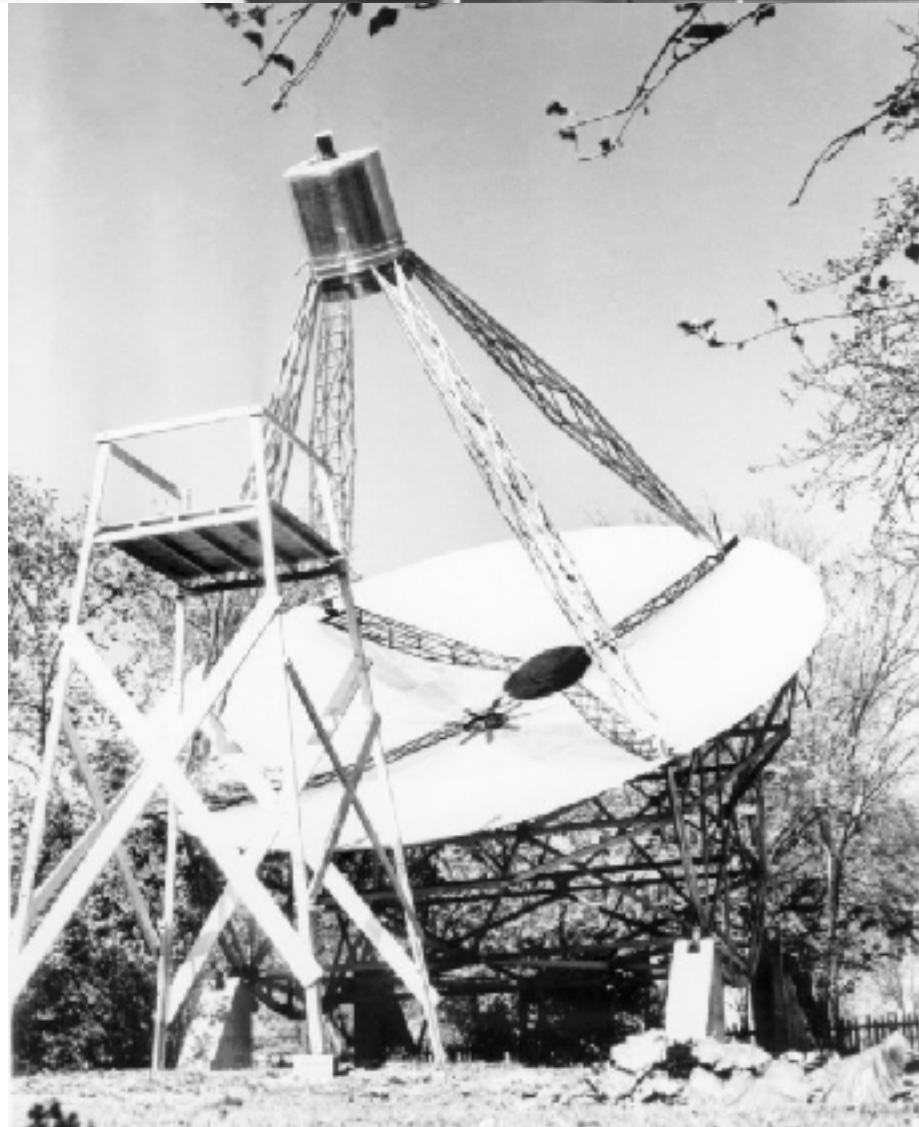
- Karl Jansky (1933, published) discovered a radio signal at 20.5 MHz that varied steady every 23 hours and 56 minutes (Sidereal day).

“The data give for the co-ordinates of the region from which the disturbance comes, a right ascension of 18 hours and declination -10 degrees.” He had detected the Galactic Centre.



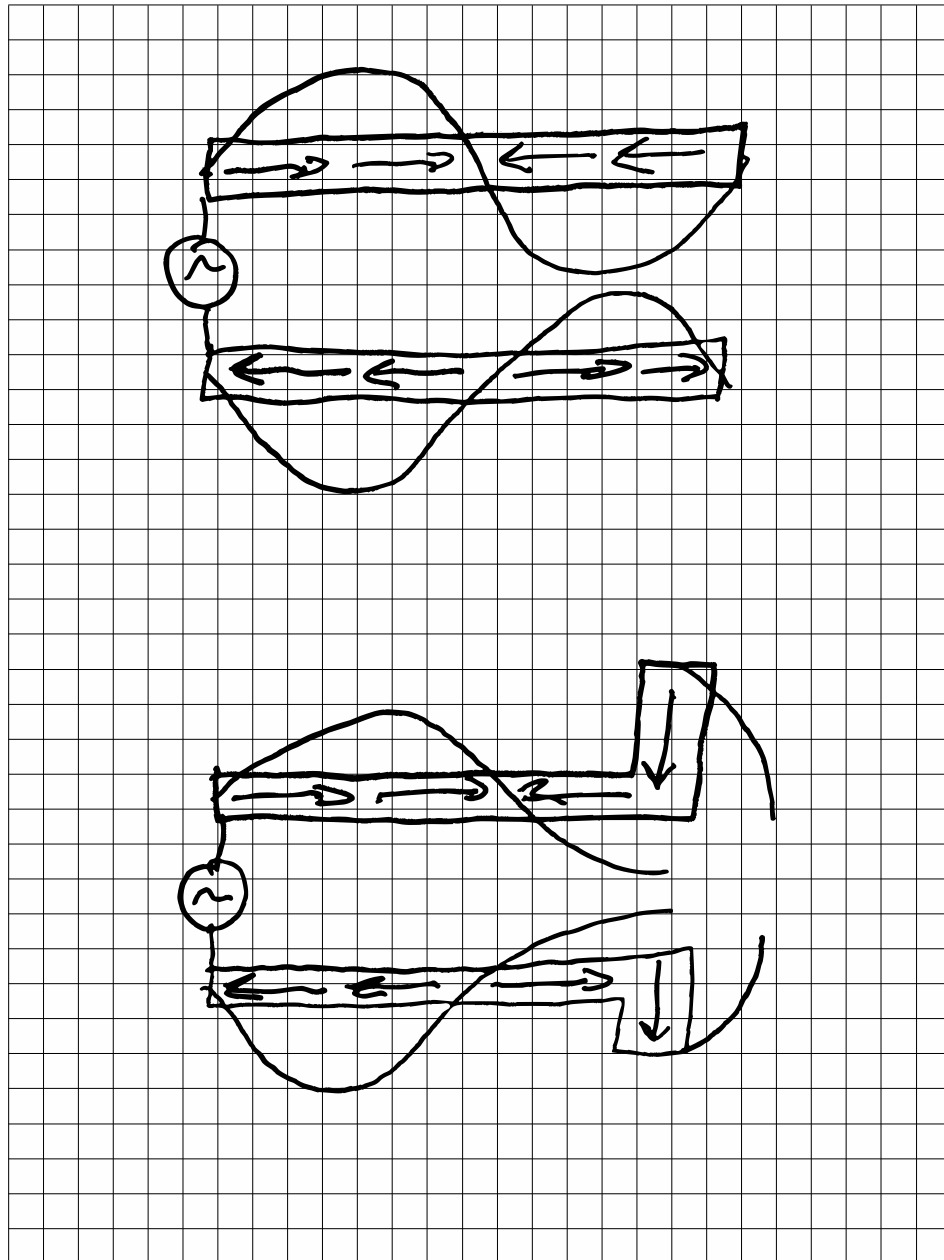


- Grote Reber (1937-39), using his own 10 m telescope, made no detection at 3300 and 910 MHz, ruling out a Planck spectrum ($B_\nu \propto \nu^2$).
- Detection made at 150 MHz, confirming Jansky's result and finding the spectrum must be non-thermal.

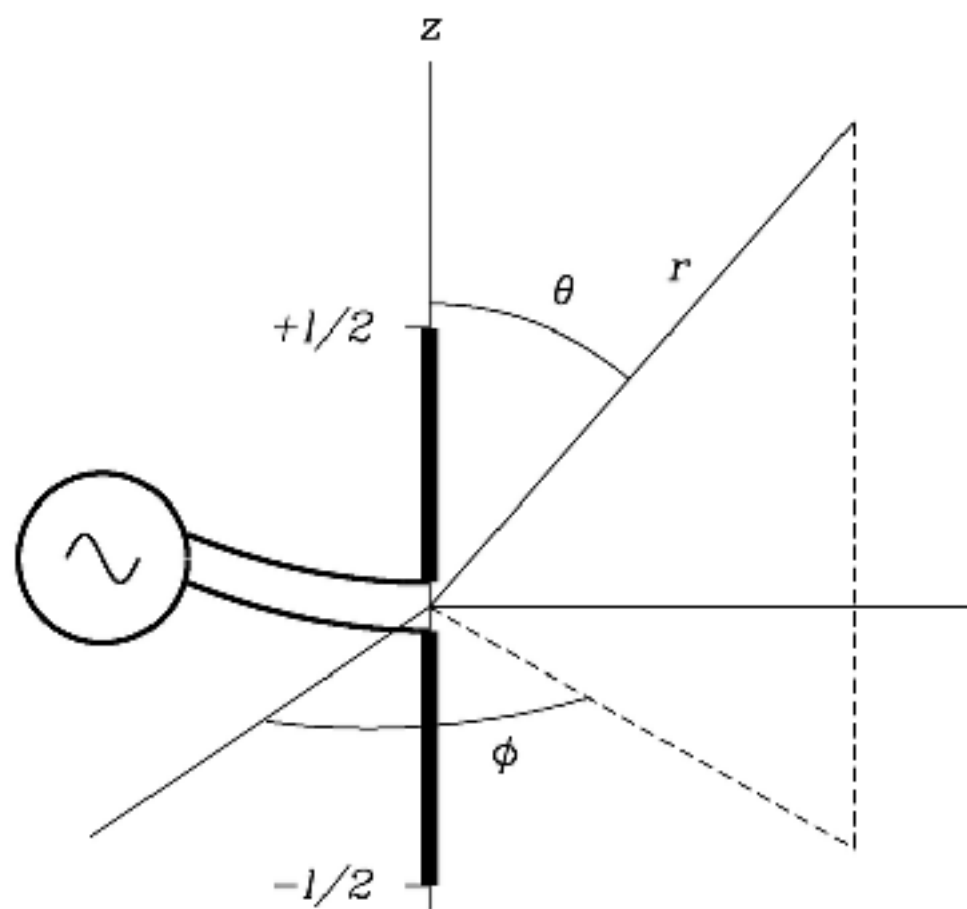


2.1 Dipole antenna fundamentals

- **Antenna:** A device for converting electromagnetic radiation in space into electrical currents (transmitting and receiving).



- Consider a simple thin-wire transition line antenna of length λ . The current along both wires is out of phase.
- By bending the edges of the transmission line ($l < \lambda / 10$), the current is now in phase, but there is a build up of charge at the ends (dipole).
- When the length is $\lambda / 2$ (or multiple), the current is a maximum at the antenna feed.



Consider a Hertzian small ($l \ll \lambda$) dipole transmitter (same as for a receiving dipole, but easier to understand).

Two co-linear conductors (e.g. wires, conducting rods), driven by a current source at the gap. The driving current I is a time varying sinusoidally with angular frequency,

$$\omega = 2\pi\nu$$

$$I = I_0 \cos(\omega t) = I_0 e^{-i\omega t}$$

(Only consider the real part of $e^{-i\omega t} = \cos(\omega t) + i \sin(\omega t)$)

The time varying current density is defined as, $J = \frac{I}{q} = \frac{I_0}{q} e^{-i\omega t}$ inside the dipole,

and $J = 0$ outside the dipole.

- We want to measure the power radiated from such an antenna, so we calculate,
 1. The electromagnetic vector potential A ,
 2. The magnetic field induction B , and hence the magnetic field intensity H ,
 3. The electric field intensity E ,
 4. The Poynting flux S ,

1. The electromagnetic vector potential

The induced magnetic field B is related to the vector potential by,

$$\vec{B} = \nabla \times \vec{A}$$

where,

$$\vec{A}(x) = \frac{\mu_0}{4\pi} \int \int \int \vec{J}(x) \frac{e^{ik|x-x'|}}{|x-x'|} d^3x'$$

i.e., the integral of the current density over the volume of the dipole ($dV = q \, dz$).

The current runs from $z = -\Delta l / 2$ and $z = +\Delta l / 2$ along the z -axis, thus

$$\begin{array}{ll} \vec{J}_x = 0 & \text{and} \quad \vec{A}_x = 0 \\ \vec{J}_y = 0 & \text{and} \quad \vec{A}_y = 0 \end{array} \quad \text{only} \quad \vec{J}_z = \frac{I}{q} e^{-i\omega t} \quad \text{is non-zero.}$$

Therefore, our vector potential becomes,

$$\begin{aligned}\vec{A}_z &= \frac{\mu_0}{4\pi} \int_{-\Delta l/2}^{+\Delta l/2} \frac{I(z)}{q} e^{-i\omega t} \frac{e^{ikr}}{r} q dz \\ &= \frac{\mu_0}{4\pi} \frac{e^{-i(\omega t - kr)}}{r} \int_{-\Delta l/2}^{+\Delta l/2} I(z) dz\end{aligned}$$

If the current is constant,

$$\int_{-\Delta l/2}^{+\Delta l/2} I(z) dz = I [z]_{-\Delta l/2}^{+\Delta l/2} = I \Delta l$$

Therefore, our vector potential for a constant current is,

$$\vec{A}_z = \frac{\mu_0}{4\pi} \frac{e^{-i(\omega t - kr)}}{r} I \Delta l$$

2. The magnetic induction is related to the magnetic vector potential via,

$$\vec{B} = \nabla \times \vec{A}$$

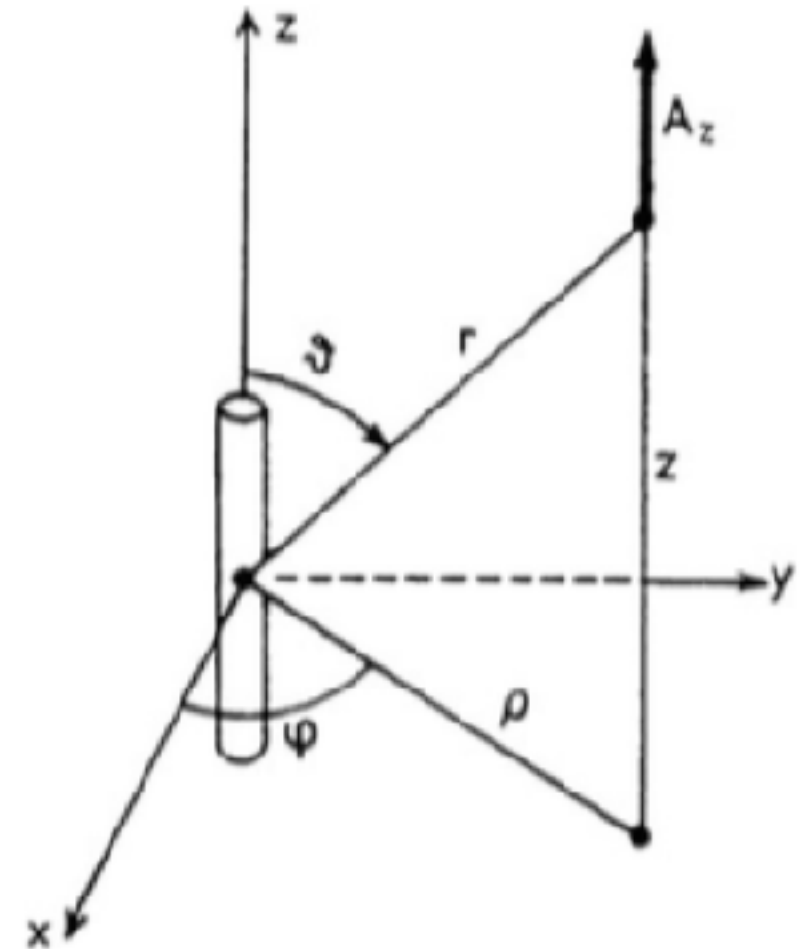
We can de-compose the curl of A into three orthogonal cylindrical co-ordinates (ρ, ψ, z) , using standard definitions,

$$(\nabla \times \vec{A})_\rho = \frac{1}{\rho} \frac{\partial A_z}{\partial \psi} - \frac{\partial A_\psi}{\partial z}$$

$$(\nabla \times \vec{A})_\psi = \frac{\partial A_\rho}{\partial z} - \frac{\partial A_z}{\partial \rho}$$

$$(\nabla \times \vec{A})_z = \frac{1}{\rho} \left(\frac{\partial(\rho A_\psi)}{\partial \rho} - \frac{\partial A_\rho}{\partial \psi} \right)$$

As $A_\rho = A_\psi = 0$, the B-field must be perpendicular to the vector potential (A_z).



For simplicity lets evaluate,

$$B_\psi = (\nabla \times \vec{A})_\psi = \frac{\partial A_\rho}{\partial z} - \frac{\partial A_z}{\partial \rho} = -\frac{\partial A_z}{\partial \rho} = -\frac{\partial A_z}{\partial r} \frac{\partial r}{\partial \rho}$$

In the cylindrical system,

$$r^2 = \rho^2 + z^2 \quad r = (\rho^2 + z^2)^{1/2}$$

$$\frac{\partial r}{\partial \rho} = \frac{1}{2}(\rho^2 + z^2)^{-1/2} 2\rho = \frac{\rho}{r} = \sin \theta$$

Next,

$$\frac{\partial A_z}{\partial r} = \frac{\mu_0}{4\pi} I \Delta l e^{-i\omega t} \frac{\partial}{\partial r} \left[\frac{e^{ikr}}{r} \right]$$

We solve this using the quotient rule,

$$\left[\frac{u(r)}{v(r)} \right] = \frac{u'(r)v(r) - v'(r)u(r)}{v(r)^2} \quad \begin{array}{ll} u(r) = e^{ikr} & v(r) = r \\ u'(r) = ik e^{ikr} & v'(r) = 1 \end{array}$$

$$\frac{\partial}{\partial r} \left[\frac{e^{ikr}}{r} \right] = \frac{ik e^{ikr} \cdot r - 1 \cdot e^{ikr}}{r^2} = \frac{(ikr - 1)e^{ikr}}{r^2}$$

Therefore our B -field in the ψ direction becomes,

$$B_\psi = -\frac{\partial A_z}{\partial r} \frac{\partial r}{\partial \rho} = -ik \frac{\mu_0}{4\pi} I \Delta l \frac{\sin \theta}{r} \left(1 - \frac{1}{ikr} \right) e^{-i(\omega t - kr)}$$

Since,

$$k = \frac{2\pi}{\lambda}$$

$$B_\psi = -i \mu_0 \frac{I \Delta l}{2\lambda} \frac{\sin \theta}{r} \left(1 - \frac{1}{ikr} \right) e^{-i(\omega t - kr)}$$

which, from the materials equations, gives for the magnetic field intensity,

$$B = \mu_0 H$$

$$H_\psi = -i \frac{I \Delta l}{2\lambda} \frac{\sin \theta}{r} \left(1 - \frac{1}{ikr} \right) e^{-i(\omega t - kr)}$$

Again, the magnetic field intensity is perpendicular to the vector potential, that is, perpendicular to the element.

3. Now, let's consider the electric field intensity. From Maxwell's equations,

$$\nabla \times \vec{H} = \vec{J} + \epsilon_0 \frac{\partial \vec{E}}{\partial t}$$

which, because we are away from the current element ($J = 0$), simplifies to,

$$\nabla \times \vec{H} = \epsilon_0 \frac{\partial \vec{E}}{\partial t}$$

We are dealing with harmonic waves of the form,

$$E(r, t) = E_0 e^{-i(\omega t - kr)}$$

$$\dot{E}(r, t) = E_0 e^{-i(\omega t - kr)} \cdot -i\omega = -i\omega E(r, t)$$

Therefore,

$$E = -\frac{1}{i\omega\epsilon_0} \nabla \times \vec{H}$$

To evaluate E , we must determine the curl of H , but as in the case of the B-field, only the H_ψ terms have non-zero entries.

From spherical co-ordinates, the only relevant term of the curl of H is,

$$(\nabla \times H)_\theta = -\frac{1}{r} \frac{\partial(rH_\psi)}{\partial r}$$

Note also, that the resulting E -field is in terms of θ and is perpendicular to the H -field, as expected for electromagnetic plane waves.

$$\begin{aligned} rH_\psi &= -i \frac{I\Delta l}{2\lambda} \sin \theta \left(1 - \frac{1}{ikr} \right) e^{-i(\omega t - kr)} \\ &= -i \frac{I\Delta l}{2\lambda} \sin \theta e^{-i\omega t} \left(e^{ikr} - \frac{e^{ikr}}{ikr} \right) \\ \frac{\partial(rH_\psi)}{\partial r} &= -i \frac{I\Delta l}{2\lambda} \sin \theta e^{-i\omega t} \frac{\partial}{\partial r} \left(e^{ikr} - \frac{e^{ikr}}{ikr} \right) \end{aligned}$$

We solve this using the quotient rule,

$$\left[\frac{u(r)}{v(r)} \right] = \frac{u'(r)v(r) - v'(r)u(r)}{v(r)^2} \quad \begin{array}{ll} u(r) = e^{ikr} & v(r) = ikr \\ u'(r) = ik e^{ikr} & v'(r) = ik \end{array}$$

$$\begin{aligned}\frac{\partial}{\partial r} \left(e^{ikr} - \frac{e^{ikr}}{ikr} \right) &= ik e^{ikr} - \left(\frac{ik e^{ikr} \cdot ikr - ik \cdot e^{ikr}}{(ikr)^2} \right) \\ &= ik e^{ikr} \left(1 - \frac{1}{ikr} + \frac{1}{(ikr)^2} \right)\end{aligned}$$

so,

$$\frac{\partial(r H_\psi)}{\partial r} = -i \frac{I \Delta l}{2\lambda} \sin \theta e^{-i\omega t} ik e^{ikr} \left(1 - \frac{1}{ikr} + \frac{1}{(ikr)^2} \right)$$

and,

$$-\frac{1}{r} \frac{\partial(r H_\psi)}{\partial r} = i^2 k \frac{I \Delta l}{2\lambda} \frac{\sin \theta}{r} \left(1 - \frac{1}{ikr} + \frac{1}{(ikr)^2} \right) e^{-i(\omega t - kr)}$$

we find,

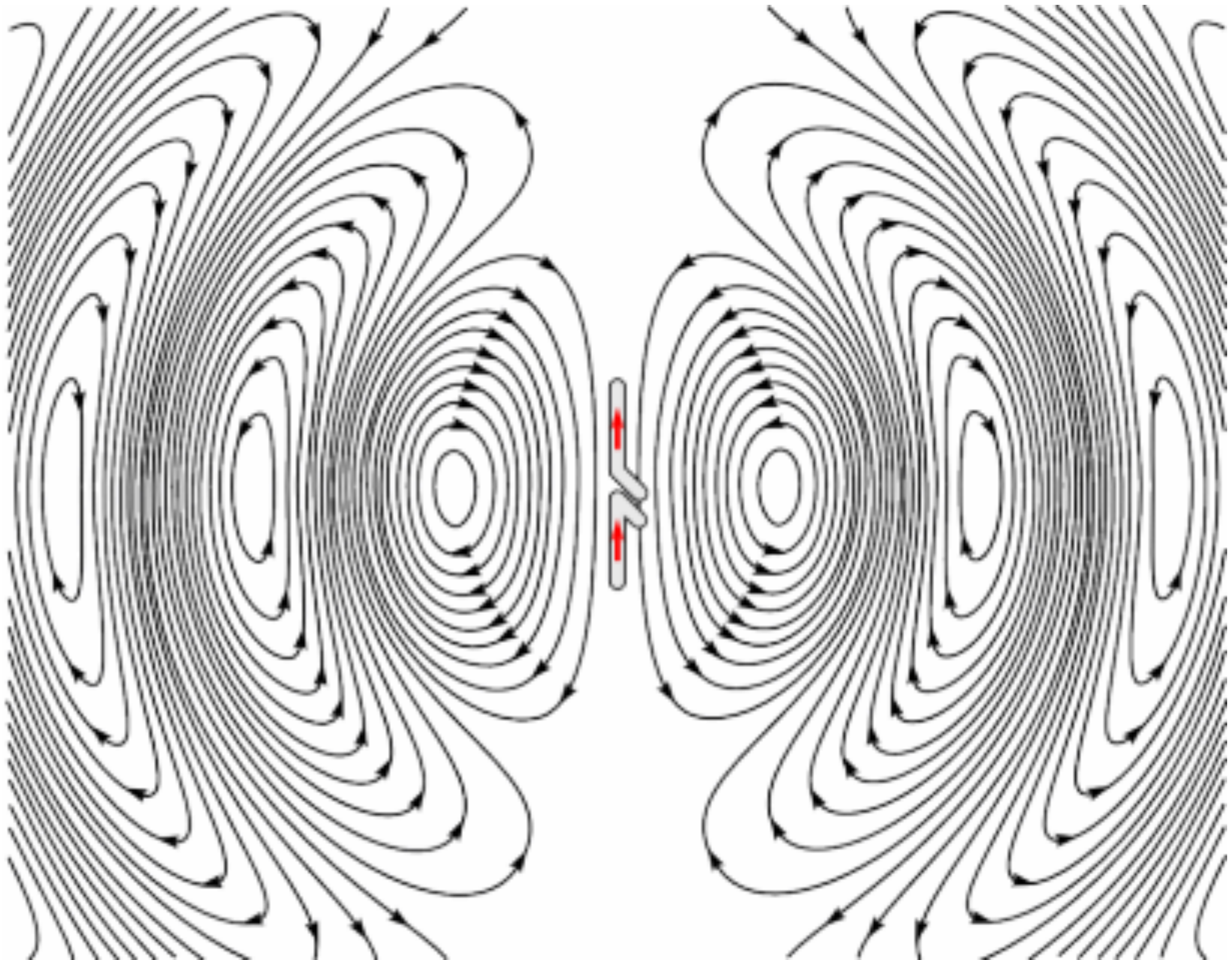
$$k = \frac{\omega}{c}$$

$$E_\theta = -i \frac{1}{c \epsilon_0} \frac{I \Delta l}{2\lambda} \frac{\sin \theta}{r} \left(1 - \frac{1}{ikr} + \frac{1}{(ikr)^2} \right) e^{-i(\omega t - kr)}$$

So the E-field can also be expressed as,

$$c = \frac{1}{\sqrt{\mu_0 \epsilon_0}}$$

$$E_\theta = -i \sqrt{\frac{\mu_0}{\epsilon_0}} \frac{I \Delta l}{2\lambda} \frac{\sin \theta}{r} \left(1 - \frac{1}{ikr} + \frac{1}{(ikr)^2} \right) e^{-i(\omega t - kr)}$$



So, our electric and magnetic fields are,

$$H_{\psi} = -i \frac{I \Delta l}{2\lambda} \frac{\sin \theta}{r} \left(1 - \frac{1}{ikr} \right) e^{-i(\omega t - kr)}$$

$$E_{\theta} = -i \sqrt{\frac{\mu_0}{\epsilon_0}} \frac{I \Delta l}{2\lambda} \frac{\sin \theta}{r} \left(1 - \frac{1}{ikr} + \frac{1}{(ikr)^2} \right) e^{-i(\omega t - kr)}$$

There are several factors that depend on the power of the distance r from the antenna,

1. $1/r$: The radiation field (dominates at large $r \gg \Delta l$).
2. $1/r^2$: The induction field
3. $1/r^3$: The static field (of the E-field).

To calculate the near-field properties, all factors must be evaluated, but in the far-field, where we measure the radiation from the antennas, the $1/r$ term dominates.

$$H_{\psi} = -i \frac{I \Delta l}{2\lambda} \frac{\sin \theta}{r} e^{-i(\omega t - kr)}$$

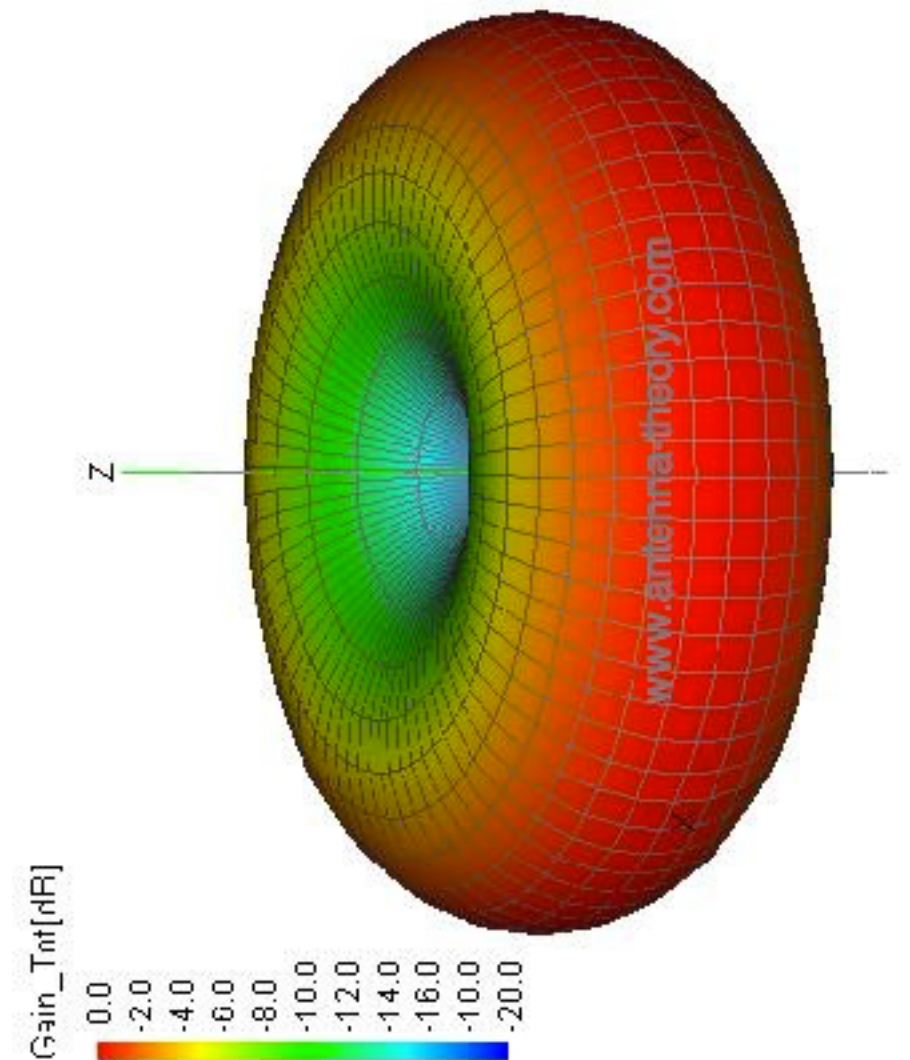
$$E_{\theta} = -i \sqrt{\frac{\mu_0}{\epsilon_0}} \frac{I \Delta l}{2\lambda} \frac{\sin \theta}{r} e^{-i(\omega t - kr)}$$

4. We can now determine the directional power per unit area in the far-field by calculating the time-averaged Poynting vector.

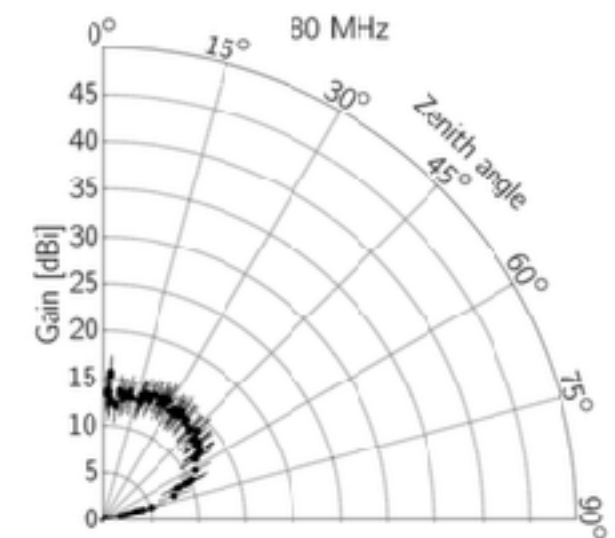
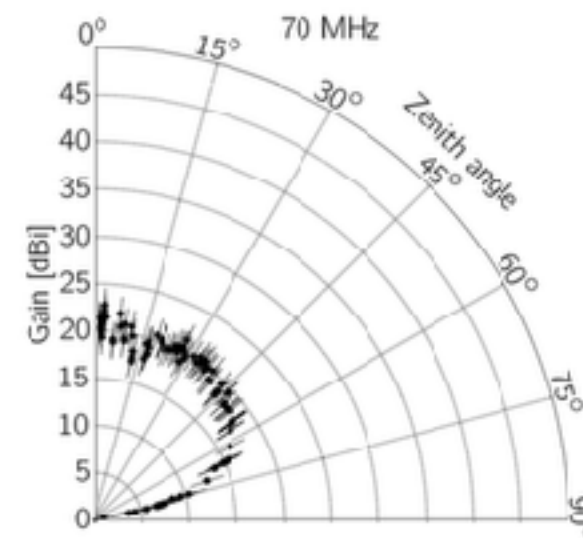
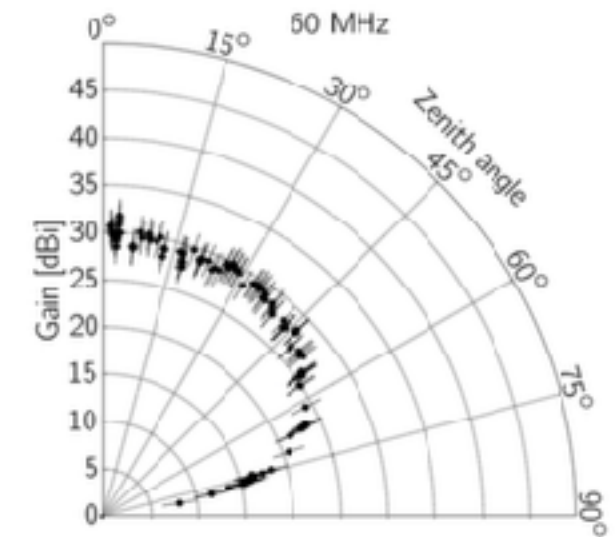
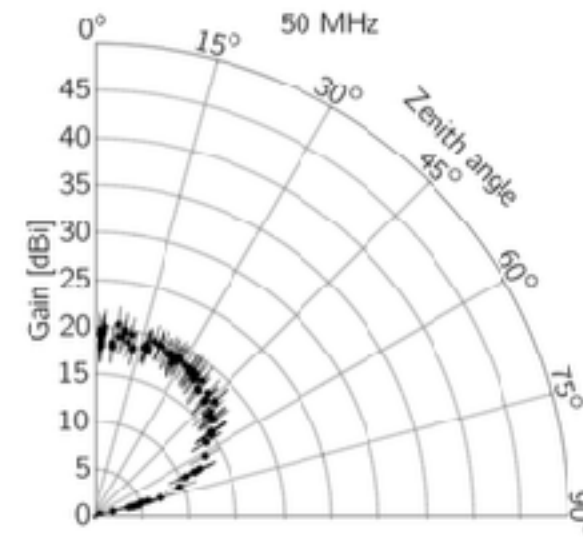
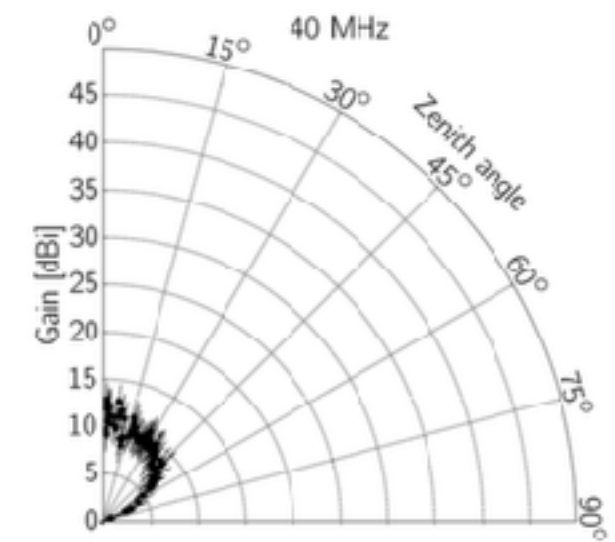
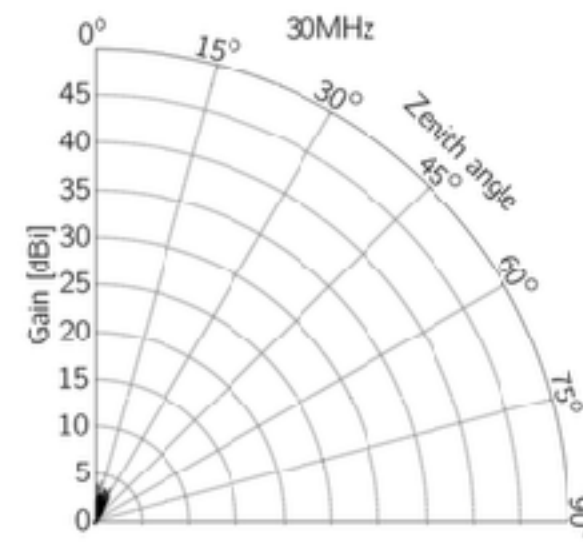
$$\begin{aligned}\langle \vec{S} \rangle &= \frac{1}{\mu_0} |\text{Re } \vec{E} \times \vec{B}^*| = |\text{Re } \vec{E} \times \vec{H}^*| \\ &= \sqrt{\frac{\mu_0}{\epsilon_0}} \left(\frac{I \Delta l}{2\lambda} \right)^2 \frac{\sin^2 \theta}{r^2} \left(\frac{1}{2} \right)\end{aligned}$$

where $\langle \cos^2(\omega t) \rangle = \frac{1}{2}$

The radiation has doughnut shaped power pattern (angular distribution of radiated power) due to dependence on $\sin^2 \theta$.

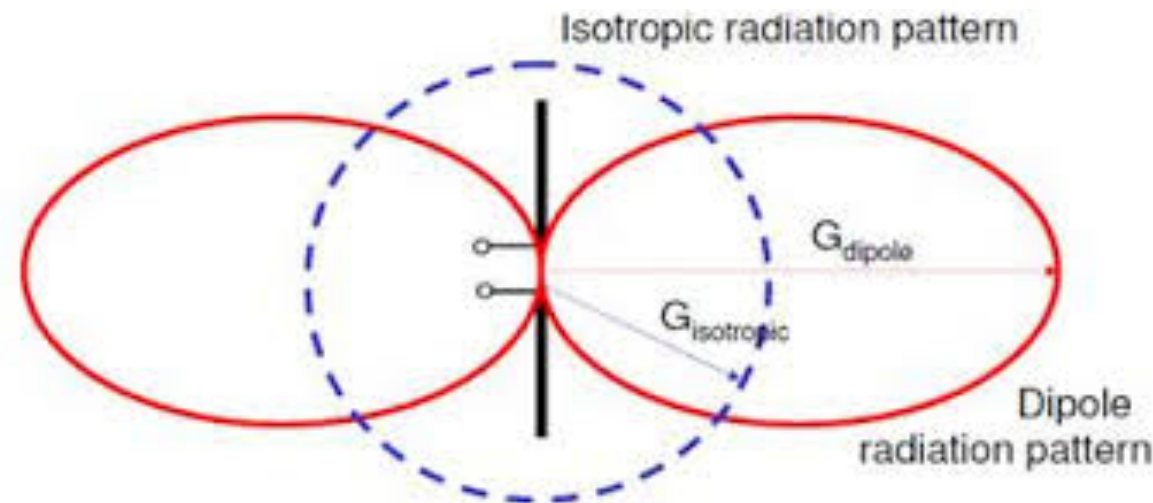


2.2 Response of the LOFAR antenna:



2.3 Power gain:

$G(\theta, \phi)$ is the power transmitted per unit solid angle in direction (θ, ϕ) divided by the power transmitted per unit solid angle from an isotropic antenna with the same total power.



- The power or gain are often expressed in logarithmic units of decibels (dB):

$$G(\text{dB}) \equiv 10 \times \log_{10}(G)$$

Worked example: What is the maximum and half power of a normalised power pattern in decibels?

Maximum power of a normalised power pattern is $P_n = 1$

$$P_n(1) = 10 \times \log_{10}(1) = 0 \text{ dB}$$

Half power of a normalised power pattern is $P_n = 0.5$

$$P_n(0.5) = 10 \times \log_{10}(0.5) = -3 \text{ dB}$$

For a lossless isotropic antenna, conservation of energy requires the directive gain averaged over all directions be,

$$\langle G \rangle \equiv \frac{\int_{\text{sphere}} G d\Omega}{\int_{\text{sphere}} d\Omega} = 1$$

Therefore, for an isotropic lossless antenna,

$$\int_{\text{sphere}} G d\Omega = \int_{\text{sphere}} d\Omega = 4\pi \quad \text{and} \quad G = 1$$

- Lossless antennas may radiate with different directional patterns, but they cannot alter the total amount of power radiated —> the gain of a lossless antenna depends only on the angular distribution of radiation from that antenna.

Key Concept: Higher the gain, the narrower the radiation pattern (directivity).

$$\Delta\Omega \approx \frac{4\pi}{G_{\text{max}}}$$

2.4 Effective collecting area (what is the collecting area of a dipole?)

- The receiving counterpart of the transmitting gain is the effective collecting area, defined as the product of the geometric area and the incident spectral power per unit area (S_ν , the flux-density),

$$\text{Effective area (m}^2\text{)} \quad A_e \equiv \frac{P_\nu}{S_{(\text{matched})}} \quad \begin{array}{l} \text{Spectral power (W Hz}^{-1}\text{)} \\ \text{Flux-density (W m}^{-2}\text{ Hz}^{-1}\text{)} \end{array}$$

Any antenna with a single output measures only one polarisation. Electric fields perpendicular to the antenna wires does not produce currents in the antenna. A pair of crossed dipoles are need to collect the power from both polarisations.

- For an unpolarised source (e.g. like a black body),

$$S_{(\text{matched})} = \frac{S}{2}$$

- The total spectral power from all directions collected by the antenna is,

$$P_\nu = A_e S_{(\text{matched})} = A_e \frac{S}{2} = \int_{4\pi} A_e(\theta, \phi) \frac{B_\nu}{2} d\Omega = kT$$

(must equal the Nyquist spectral power). From the R-J equation,

$$B_\nu = \frac{2kT}{\lambda^2} \quad P_\nu = \frac{2kT}{2\lambda^2} \int_{4\pi} A_e(\theta, \phi) d\Omega = kT$$

$$\int_{4\pi} A_e(\theta, \phi) d\Omega = \lambda^2$$

- The average collecting area is defined as

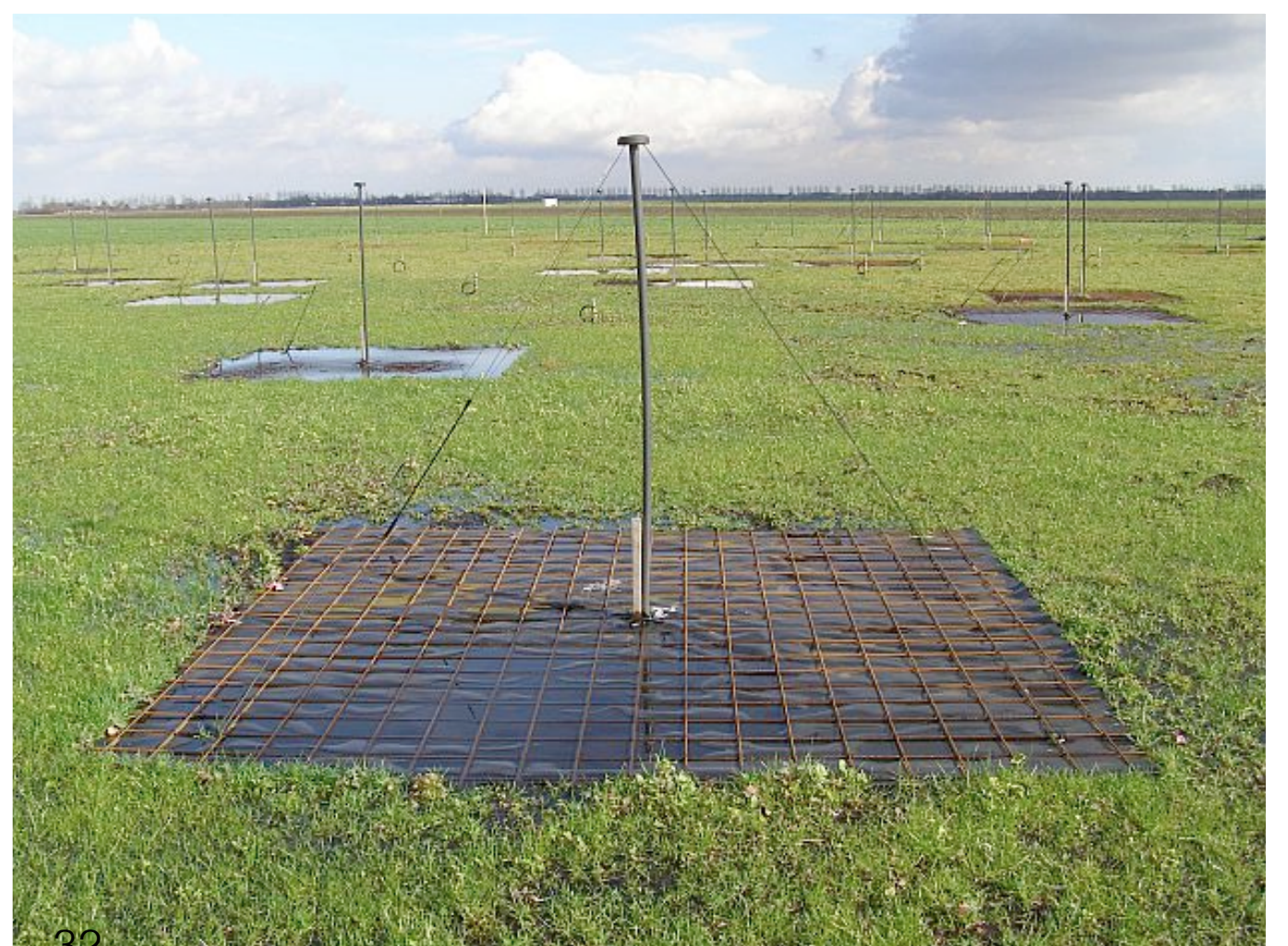
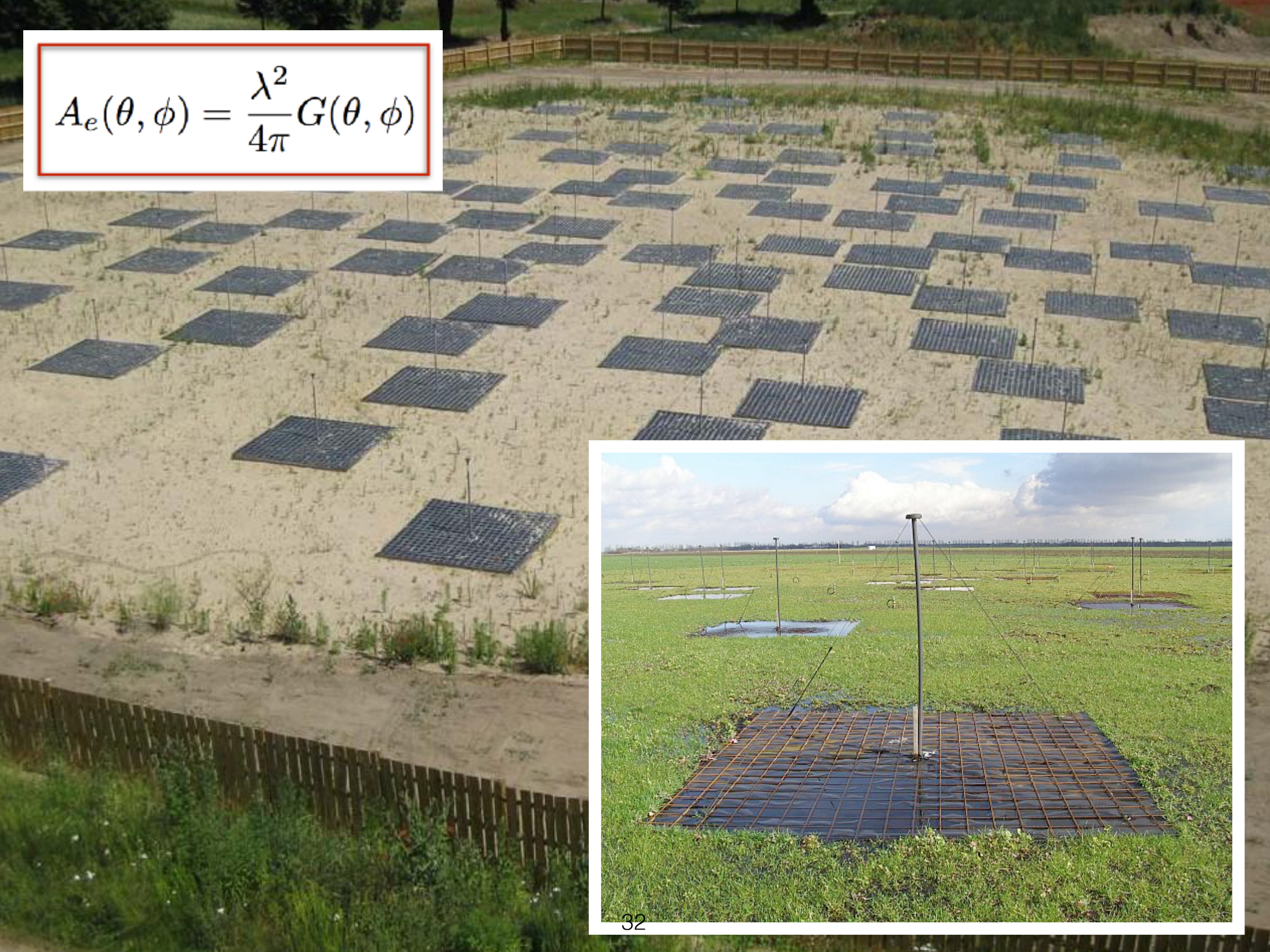
$$\langle A_e \rangle = \frac{\int_{4\pi} A_e(\theta, \phi) d\Omega}{\int_{4\pi} d\Omega}$$

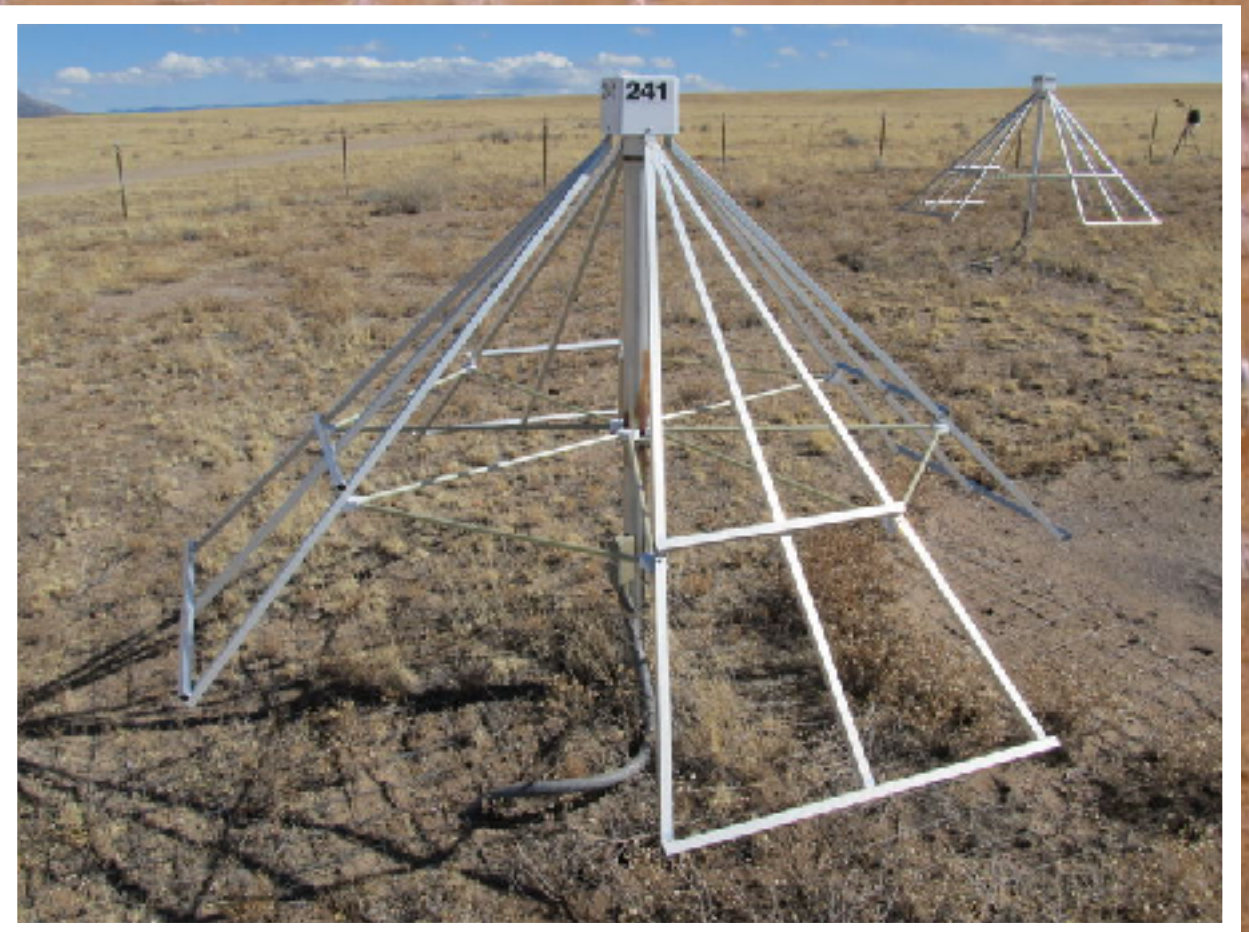
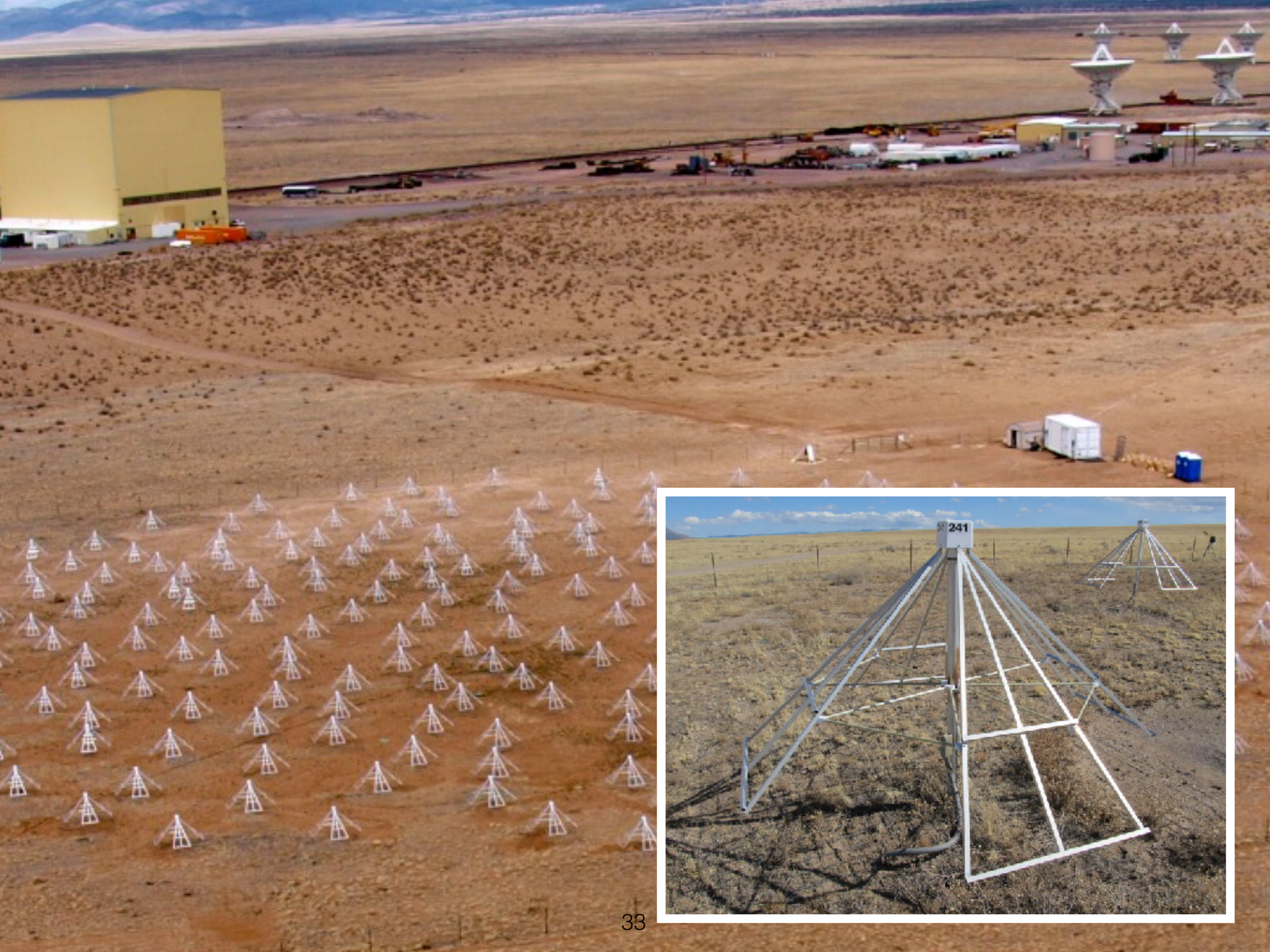
The effective collecting area is independent of the antenna environment, so this relation is valid for any type of radiation (not just black body radiation).

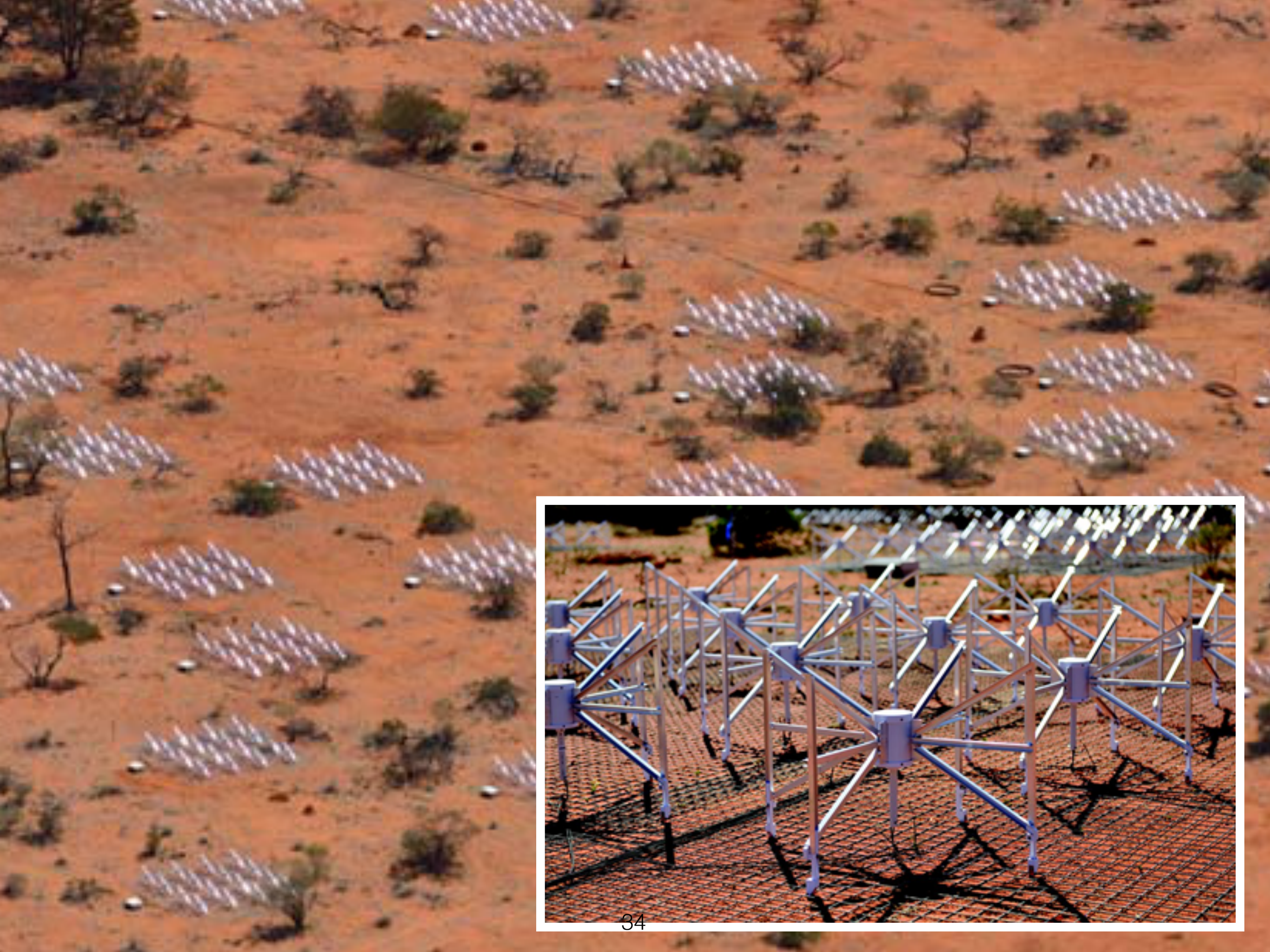
Key concept: Any antenna has the same average collecting area $\langle A_e \rangle$ that depends only on the wavelength of the radiation.

$$\langle A_e \rangle = \frac{\lambda^2}{4\pi}$$

$$A_e(\theta, \phi) = \frac{\lambda^2}{4\pi} G(\theta, \phi)$$







3.1 Interferometers

Combined telescopes

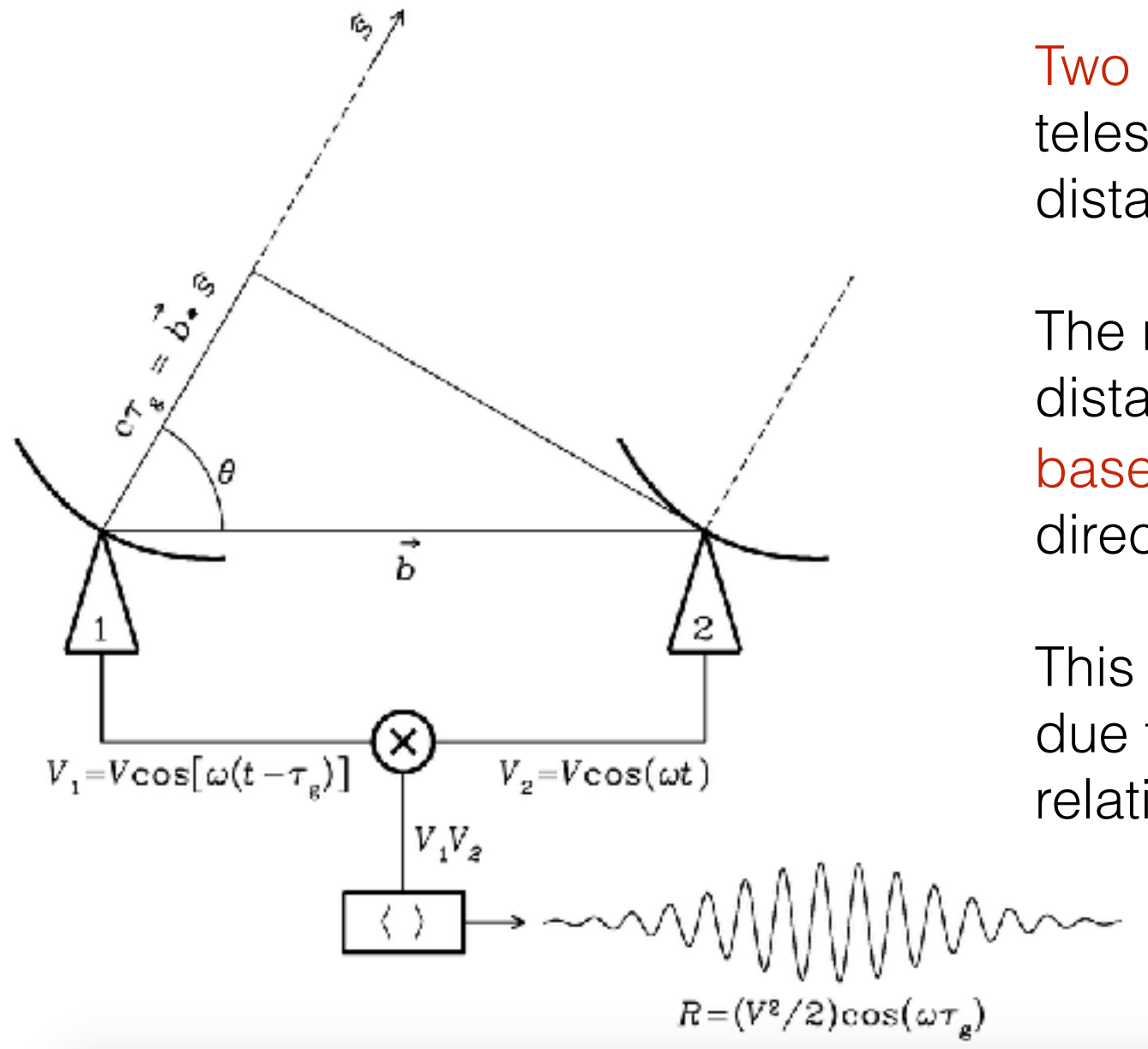
$$\theta_{\text{res}} \sim \frac{\lambda}{B}$$

Individual telescope

$$\theta_{\text{res}} \sim \frac{\lambda}{D}$$

- We can overcome this problem by correlating the signals from different telescopes to effectively increase D to an arbitrarily large value by increasing the distance between the telescopes, called the baseline length B . Now, $\theta \sim \lambda / B$.
 1. High angular resolution (down to < 1 mas; best in astronomy), e.g. VLBI.
 2. Better sensitivity (Area = $N\pi D^2 / 4$, N is number of telescopes), e.g. LOFAR, JVLA, ALMA.
 3. Large field-of-view (10s deg²) in the case of phased array feeds, e.g. WSRT-Aperitif.

3.2 A simple two-element interferometer



Two element interferometer: Two identical telescopes observe the electric field of some distant source (c.f. Young's double slit).

The radiation to antenna 1 travels an extra distance $\vec{b} \cdot \hat{s} = b \cos \theta$, where \vec{b} is the vector **baseline** length and \hat{s} a unit vector in the direction of the source.

This can be expressed as a **geometric delay** due to the projected position of the source, relative to the baseline of the antennas.

$$\tau_g = \vec{b} \cdot \hat{s} / c$$

For a **quasi-monochromatic** interferometer (responds to a narrow frequency range $\nu = 2\pi / \lambda$), the output voltages over time t from the two antennas are,

$$V_1 = V \cos[\omega(t - \tau_g)] \quad \text{and} \quad V_2 = V \cos(\omega t)$$

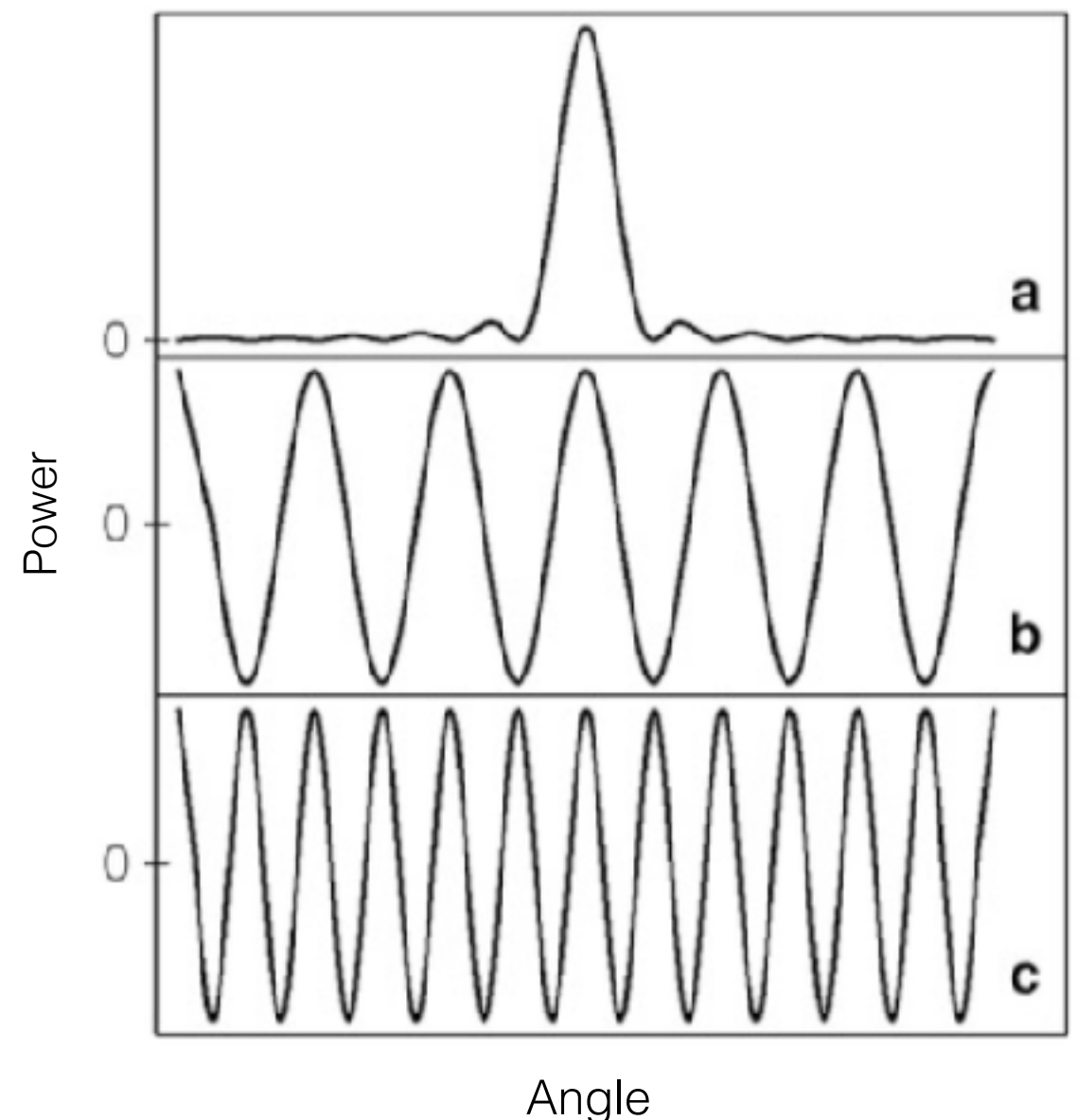
The **correlator** multiplies the voltages from the two antennas together to give,

$$V_1 V_2 = V^2 \cos[\omega(t - \tau_g)] \cos(\omega t) = \left(\frac{V^2}{2}\right) [\cos[2\omega t - \omega\tau_g] + \cos(\omega\tau_g)]$$

and then a time average $[\Delta t \gg (2\omega)^{-1}]$ to remove the high frequency component to give,

$$R = \langle V_1 V_2 \rangle = \left(\frac{V^2}{2}\right) \cos(\omega\tau_g)$$

- The power pattern of a filled aperture of diameter D with a constant illumination pattern. The FWHM of the main beam is $\sim \lambda / D$.
- The power pattern of a two-element interferometer with 2 antennas of diameter d and separation D . The side-lobe level is constant and the power is centred on 0. The FWHM of the fringes is $\sim \lambda / D$.
- The power pattern of a two-element interferometer with 2 antennas of diameter d and separation $2D$. The FWHM of the fringes is now $\sim \lambda / 2D$.



3.4 Extended sources

A spatially incoherent extended source with sky brightness $I_\nu(\hat{s})$ near frequency $\nu = \omega / 2\pi$ can be considered as the sum of independent point sources. The response of an interferometer is then,

$$R_c = \int I_\nu(\hat{s}) \cos(2\pi\nu\vec{b} \cdot \hat{s}/c) d\Omega = \int I_\nu(\hat{s}) \cos(2\pi\vec{b} \cdot \hat{s}/\lambda) d\Omega$$

Note that, the output from the correlator is a complex quantity and so far we have only considered the (real) cosine part of the signal. The (imaginary) sine component is found by inserting a 90° phase delay ($t - \tau_g - \pi/2$).

$$R_s = \int I_\nu(\hat{s}) \sin(2\pi\vec{b} \cdot \hat{s}/\lambda) d\Omega$$

It is convenient to express this in terms of complex exponentials,

$$e^{i\phi} = \cos \phi + i \sin \phi$$

Allowing us to define the **complex visibility** $V = R_c - iR_s$ as,

$$V = Ae^{-i\phi}$$

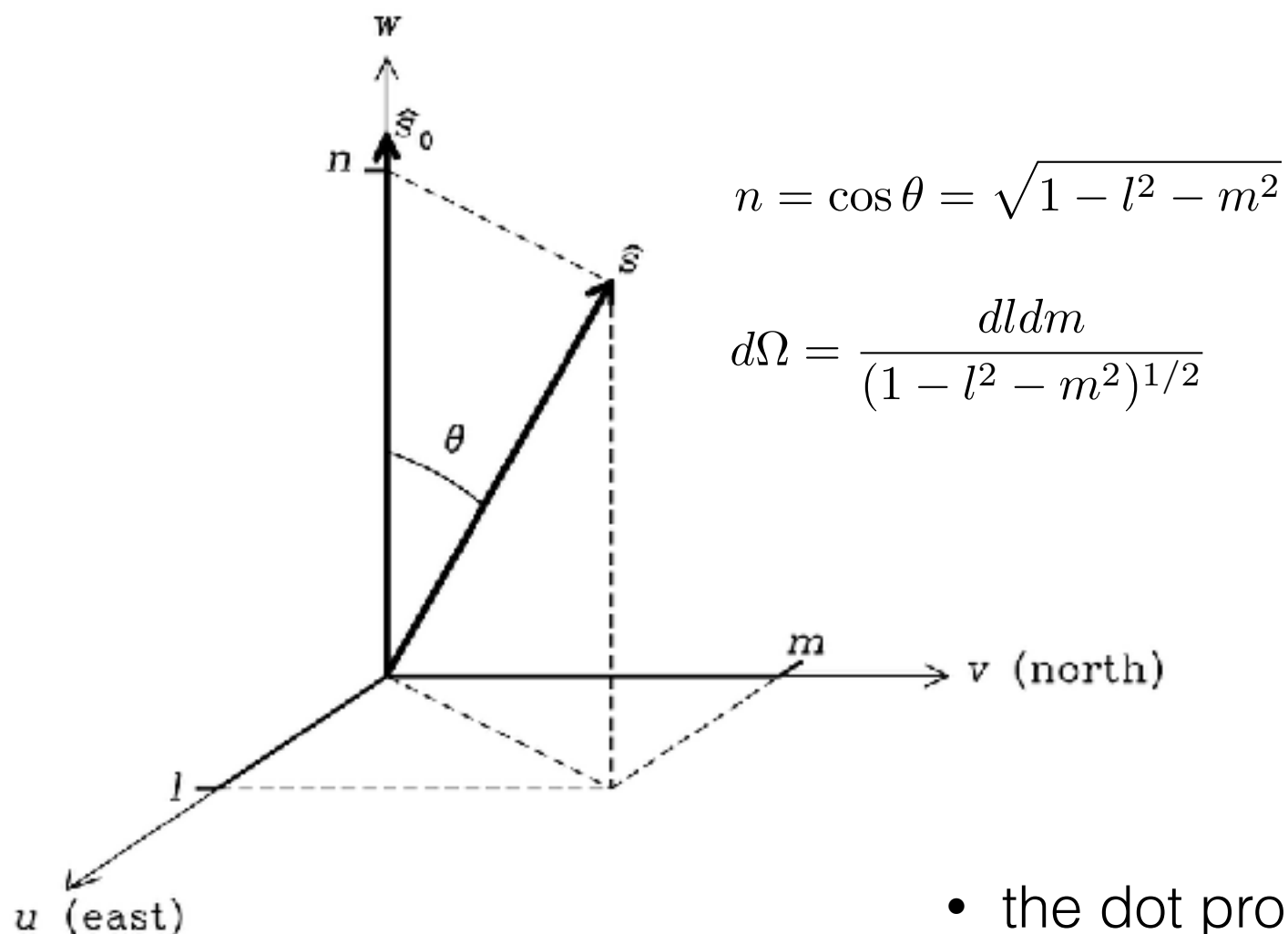
where the amplitude is, $A = (R_c^2 + R_s^2)^{1/2}$ and the phase is, $\phi = \tan^{-1}(R_s/R_c)$

So, we can write the response of a two element interferometer to an extended source with brightness distribution $I_\nu(\hat{s})$ as,

$$V_\nu = \int I_\nu(\hat{s}) \exp(-i2\pi \vec{b} \cdot \hat{s} / \lambda) d\Omega$$

3.5 General response of an interferometer

First, we define our co-ordinate systems.



- baseline

$$\frac{\vec{b}}{\lambda} = (u, v, w)$$

North-South
 East-West Up-Down

- source

$$\hat{s} = (l, m, \sqrt{1 - l^2 - m^2})$$

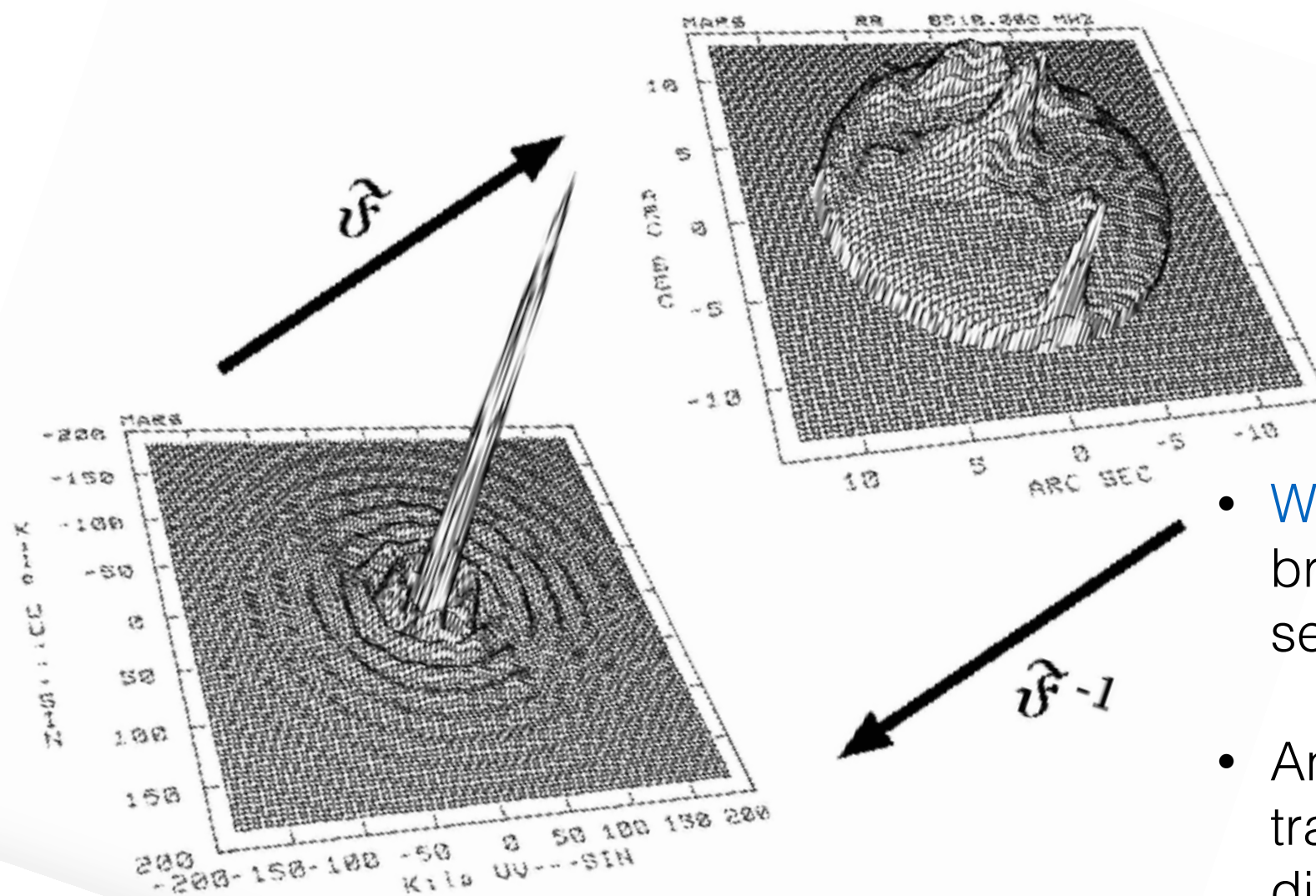
North-South
 East-West Up-Down

- the dot product $\frac{\vec{b}}{\lambda} \cdot \hat{s} = ul + vm + w\sqrt{1 - l^2 - m^2}$

We can then describe the response of an interferometer to any position in the sky as,

$$V_\nu(u, v, w) = \iint \frac{I_\nu(l, m)}{(1 - l^2 - m^2)^{1/2}} \exp[-i2\pi(ul + vm + wn)] dl dm$$

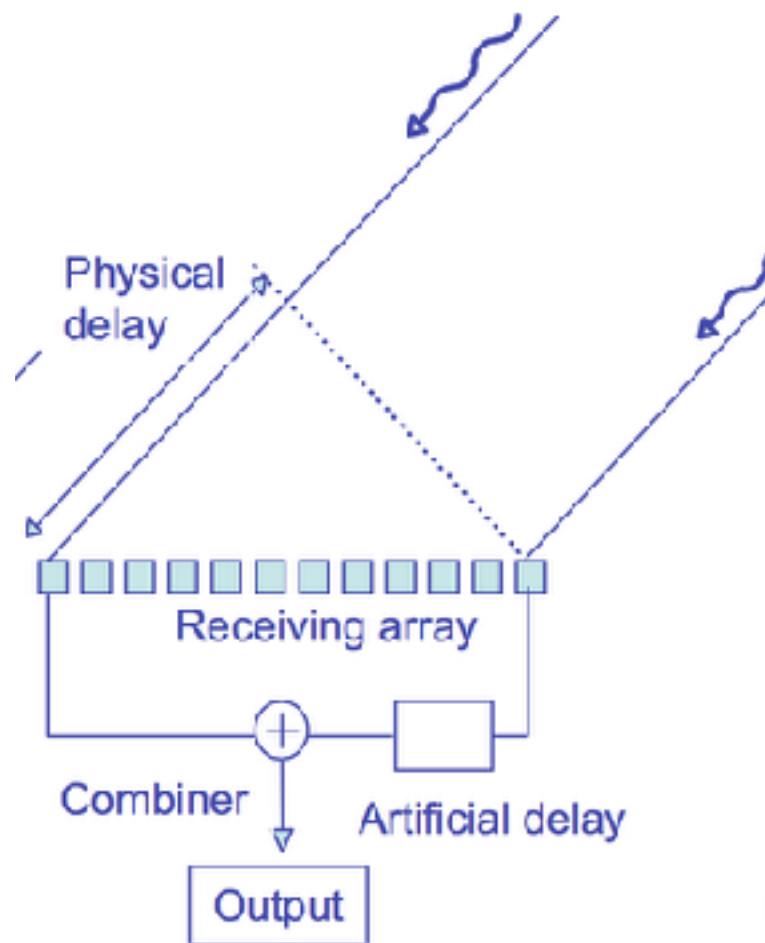
Key Concept: The response of an interferometer is the (inverse) Fourier transform of the (apparent) sky brightness distribution.



- **Worked example:** Here is the surface brightness distribution of Mars, as seen at 3.6 cm.
- An interferometer will see the Fourier transform of this surface brightness distribution.

3.6 Next generation interferometers

- We can also combine different antenna receiver elements together coherently to form an **aperture array** (e.g. LOFAR; MWA; LWA).



Tile

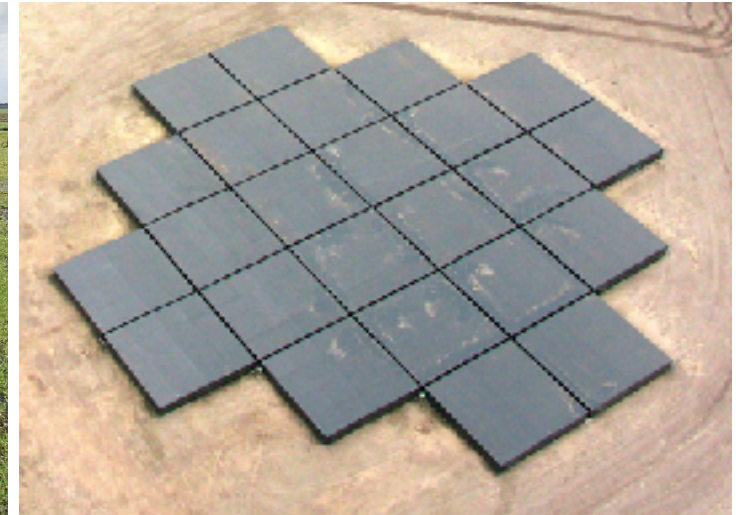
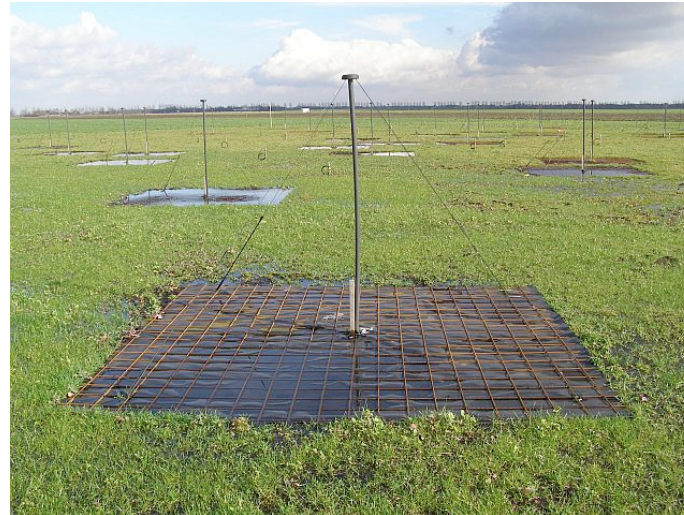
Station

Core

- Aperture array:** In the same way that an interferometer works, the receiving elements are added together by taking into account the **delay** due to the waves arriving at different times, from **different directions**.
 - Low cost (no moving parts, dipole elements).
 - Better effective area at low radio frequencies.
 - Large fields-of-view and flexible electronic beam forming.

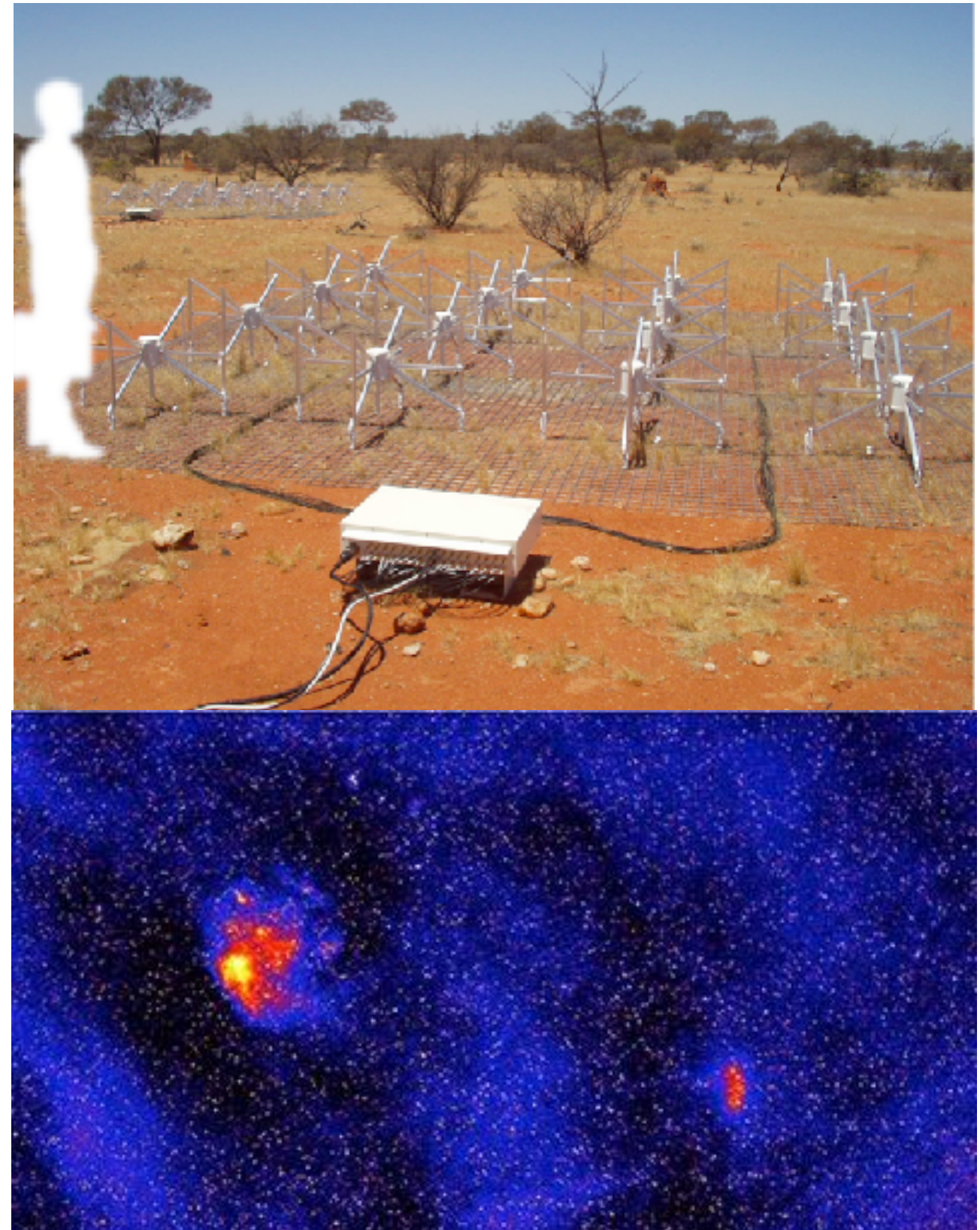
4.1 The Low Frequency Array

- International LOFAR Telescope being built by a consortium of institutes in the Netherlands, Germany, UK, France, Sweden, Poland and Ireland.
- Low Band Antenna (LBA; 10--90 MHz) - simple dipoles.
- High Band Antenna (110-180 MHz, 210-240 MHz) - tiled array.
- 96 MHz bandwidth.
- 50 Stations throughout Europe (~50 m to 1500 km baselines), resolution ~few degrees to sub-arcsec.



4.2 The Murchison Wide-Field Array

- Low frequency pathfinder based in Australia (quiet-site).
- 80--300 MHz frequency coverage, with 32 MHz instantaneous bandwidth.
- 128 tiles, with 4 x 4 dipoles (very like LOFAR).
- Max baseline to 3 km outriggers; most tiles (112) within 1.5 km.
- Wide field-of-view (15-45 degrees)
- Resolution of 2.5 to 8.5 arcmin



4.3 The Very Large Array

- Upgraded VLA, P-band (230-470 MHz).
- Receivers in place to sample down to 50 MHz.
- 27 x 25 m dish antennas with baselines up to 36 km in 4 configurations (A-D)

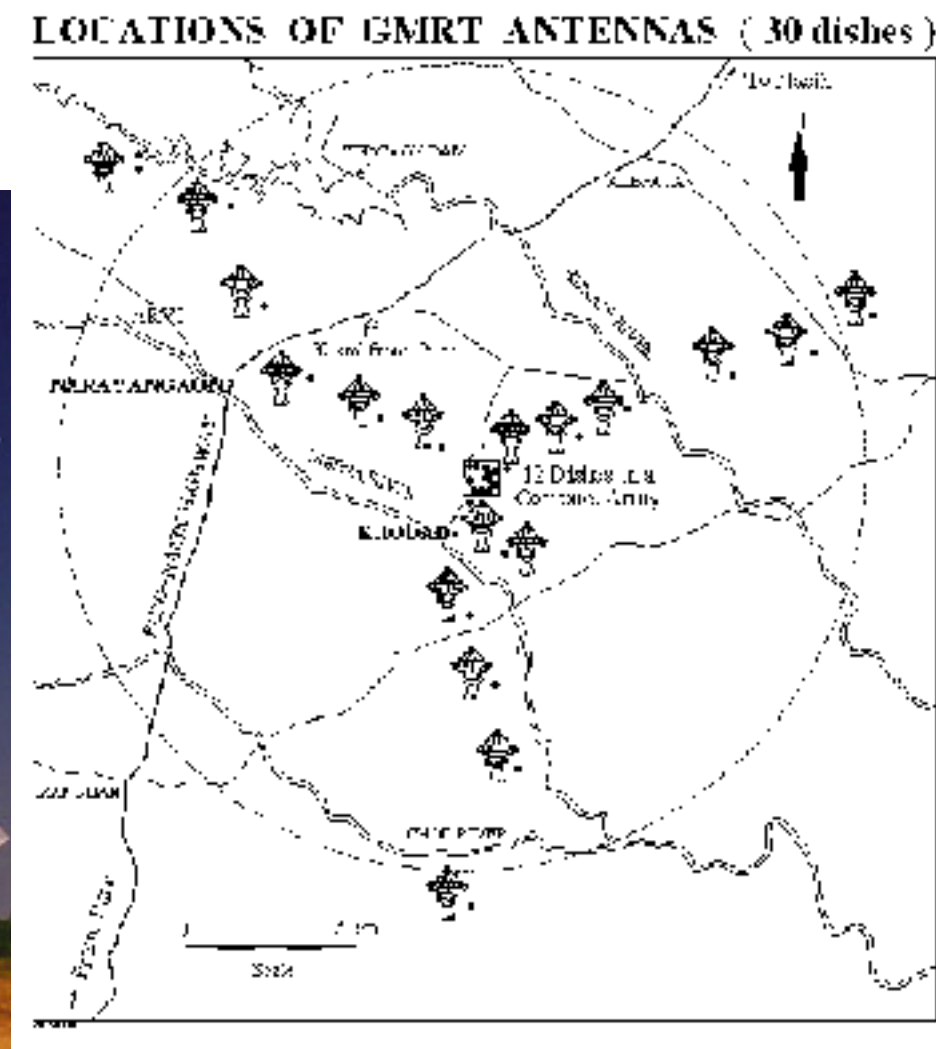


4.4 Long Wavelength Array



- 10-88 MHz; 4 simultaneous beam.
- LWA1 = 256 (+1) dual polarisation dipoles (100 x 110 m station)
- Full array; Ambitions to have baselines up to 400 km (~50 stations in NM; USA)
- LWA2 currently under construction (19 km baseline to LWA1)

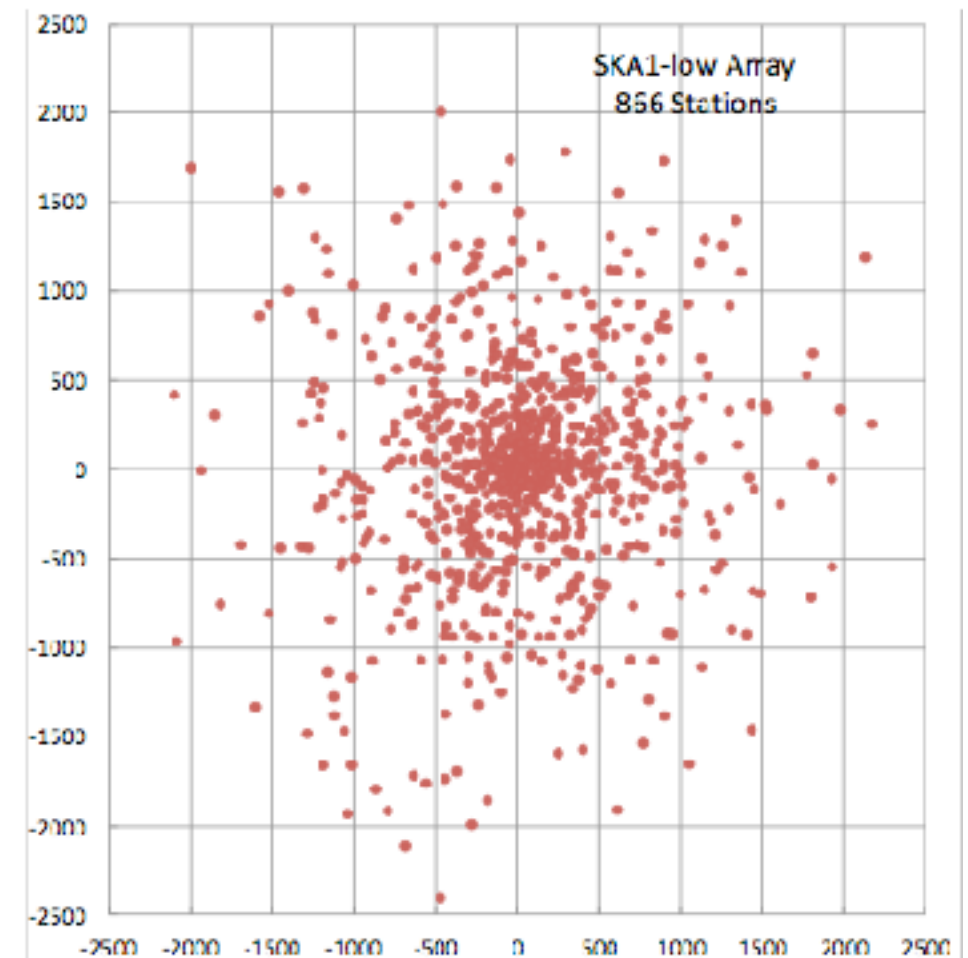
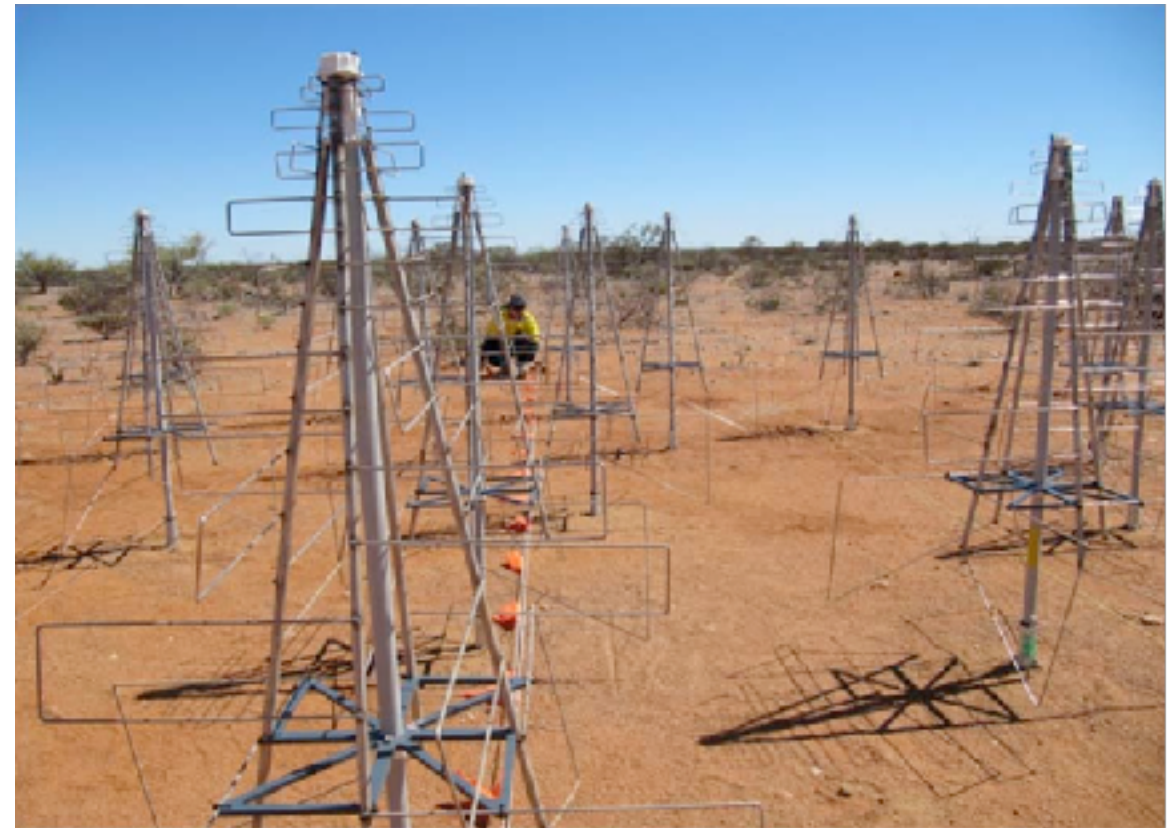
4.5 Giant Metrewave Radio Telescope



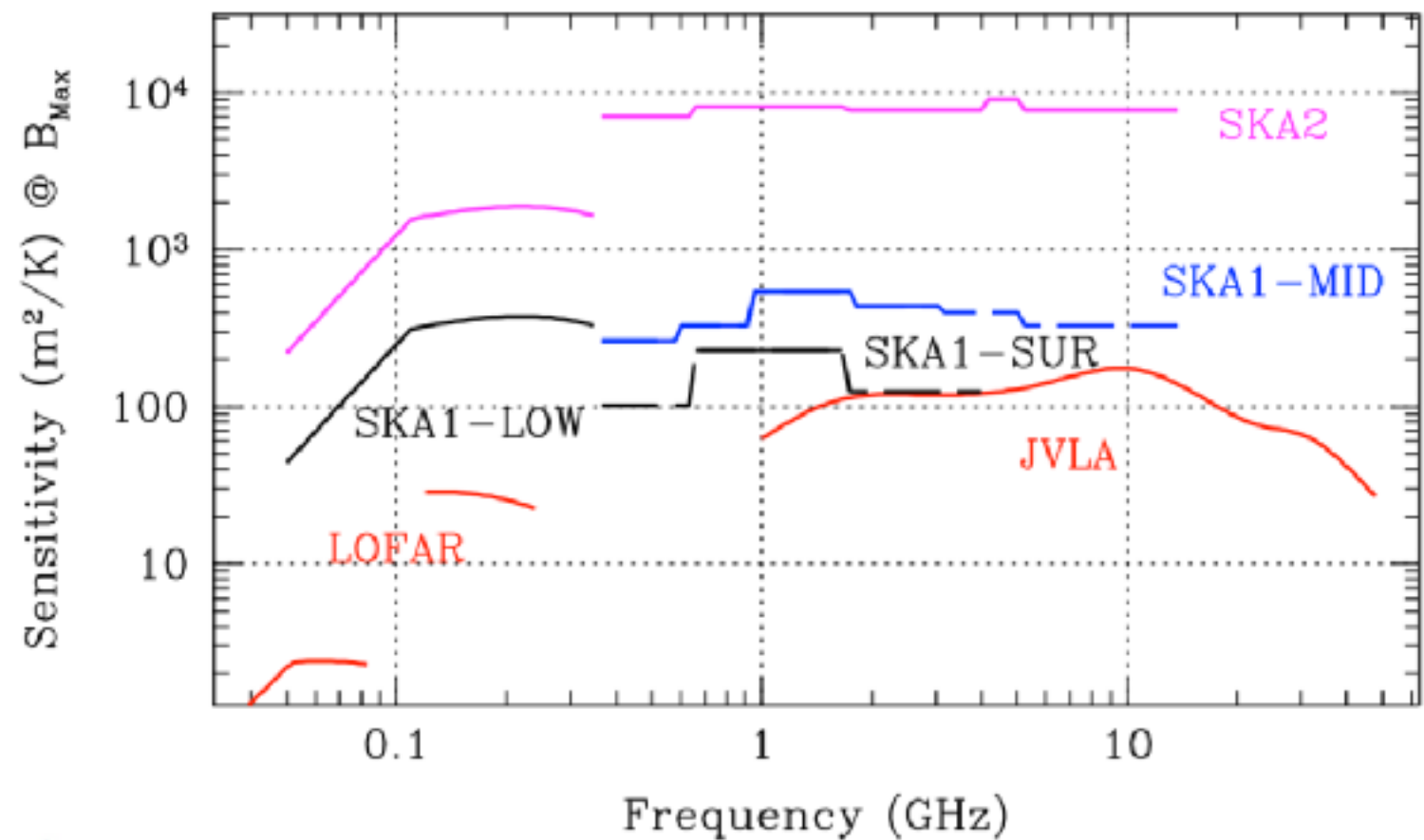
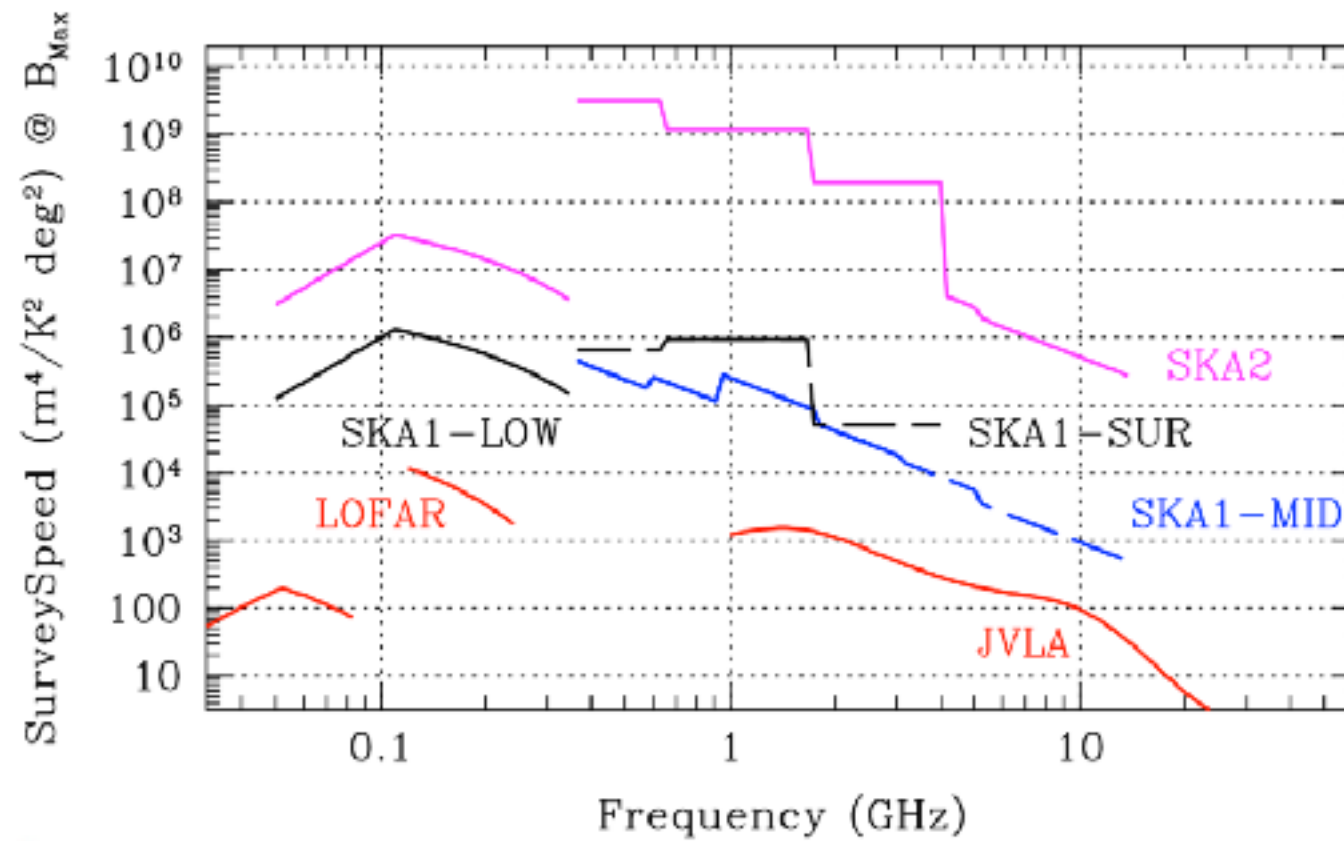
- Low frequency bands at 150, 235, 327 MHz (32 MHz bandwidth).
- 30 x 45 m antennas.
- Baselines up to 25 km
- Upgrade underway, providing contiguous 120–1500 MHz (400 MHz bandwidth).

4.6 Square Kilometre Array (SKA)

- Sparse dipoles (dual pol; similar to LOFAR).
- Freq: 50 to 350 MHz (300 MHz bandwidth).
- 130000 dipole antennas.
- 8 x more sensitive than LOFAR
- 50% collecting area at < 600 m, 75% at < 1 km.
- Spiral arms out to 50 km (100 km baselines), containing only $\sim 4\%$ of the collecting area.
- Dense core for EoR and Pulsar timing experiments (1 mK brightness temperature for 5 arcmin structures).
- $A_{\text{eff}} / T_{\text{sys}} \sim 1000 \text{ m}^2 / \text{K}$ (> 100 MHz).



4.6 Square Kilometre Array (SKA)



Summary

1. Radio astronomy had its origins at low frequencies, and after a successful diversion to higher frequencies, attention is returning to < 350 MHz.
 - Modern dipoles still quite simple (cheap, easily replaced, large fields-of-view, large effective collecting area).
 - Need large computing power for correlation and data processing (see lecture on LOFAR Overview).
2. Interferometry is essential for competitive low frequency science.
 - Increases angular resolution and sensitivity at cost to filtering structure on large angular-scales and complicating the point-spread function.
 - Requires detailed calibration (see lectures on Calibration, Error Analysis and Ionosphere) and special wide-field, wide-bandwidth imaging techniques (see lectures on Imaging).
3. Several important low frequency radio telescopes available (LOFAR, LWA, GMRT, VLA, MWA) and upcoming (SKA).